

# Intelligent systems for anomaly detection of real cases for production optimizing

José Luis Calvo Rolle

UNED 2025 - Madrid



Grupo de Investigación  
Ciencia y Técnica Cibernética



UNIVERSIDADE DA CORUÑA

# Summary

- 1 Introduction
- 2 Digital Twin research line CEMI (Navantia-UDC)
- 3 Based on model
- 4 Based on One-class techniques
- 5 Our proposals for Fault Detection accomplishing
- 6 Conclusions and future works

# Introduction

# Introduction

Anomaly detection, fault detection, ... to anomaly explanation

- What is an anomaly?
- What is a fault?
- What is the difference between an anomaly and a failure?
- What is anomaly/fault detection?
- Is the anomaly/fault explanation possible?
- The Fault-Tolerant Systems

## Introduction

Anomaly detection, fault detection, ... to anomaly explanation

Under a general point of view, anomaly detection, or fault detection, basically is the outlier identification as an observation, event, or data point that deviates from what is normal or expected, making it inconsistent with the rest of the data set.

Detecting anomalies or faults can have very important benefits.

# Is it a simple task?

# Introduction

Anomaly detection, fault detection, ... to anomaly explanation

It could be easy:



# Introduction

Anomaly detection, fault detection, ... to anomaly explanation

It could be not easy:



Where's Wally?

# Introduction

Anomaly detection, fault detection, ... to anomaly explanation

What happens if the problem is, for instance:

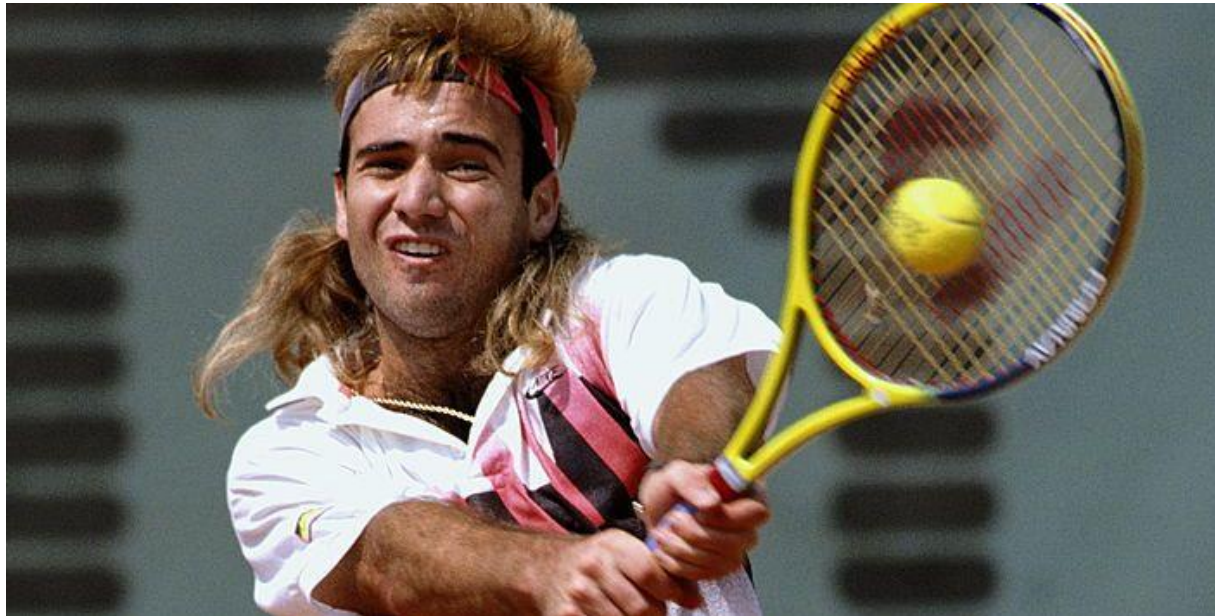
- Variable
- Not linear
- Multivariable dependent
- ....



# Introduction

Anomaly detection, fault detection, ... to anomaly explanation

Andre Agassi VS Boris Becker



<https://www.puntodebreak.com/2020/04/30/lengua-becker-secreto-mejor-guardado-Agassi>

# Introduction

Anomaly detection, fault detection, ... to anomaly explanation

The unconscious secret of Boris Becker's tongue

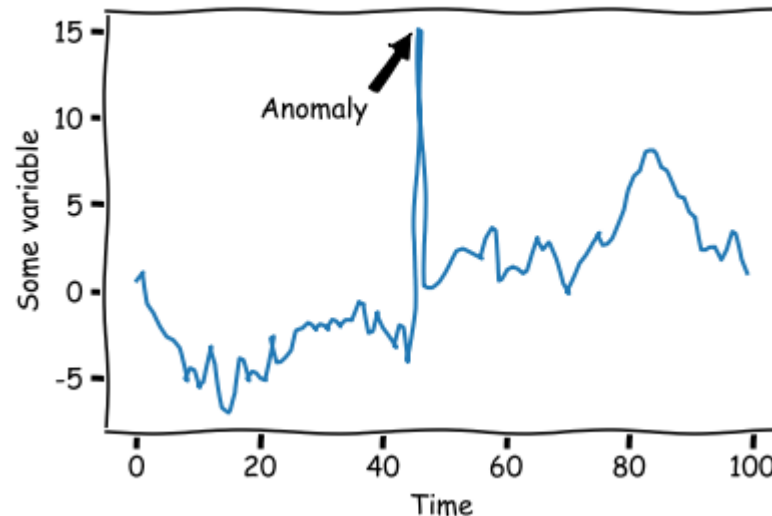


# Introduction

Anomaly detection, fault detection, ... to anomaly explanation

Anomaly detection has a long history in the field of statistics.

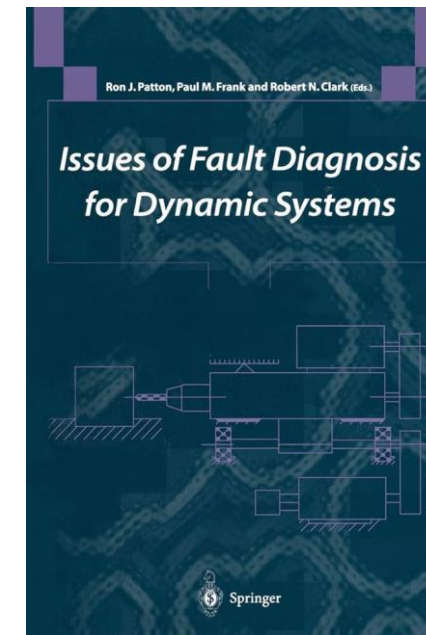
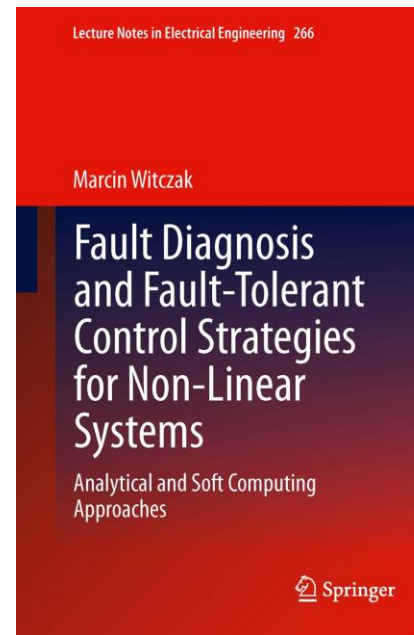
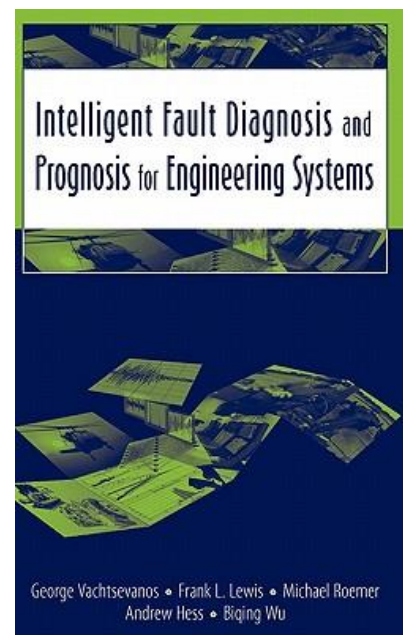
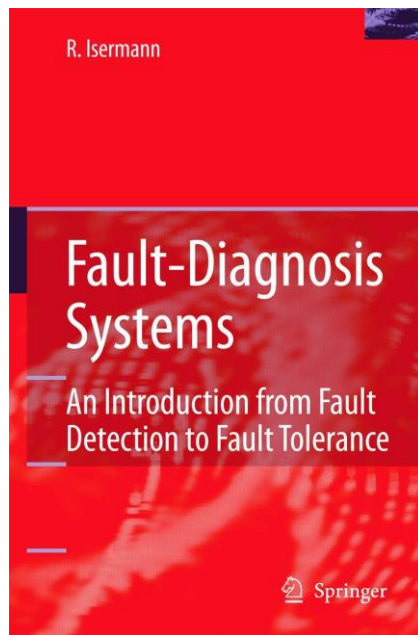
Analysts and scientists studied datasets and specially graphs, looking for anything that seemed abnormal.



# Introduction

Anomaly detection, fault detection, ... to anomaly explanation

It is a very important field in control systems.



## Introduction

Anomaly detection, fault detection, ... to anomaly explanation

Under a paradigm of control systems, in addition to the detection of faults and anomalies, the next issues are very important:

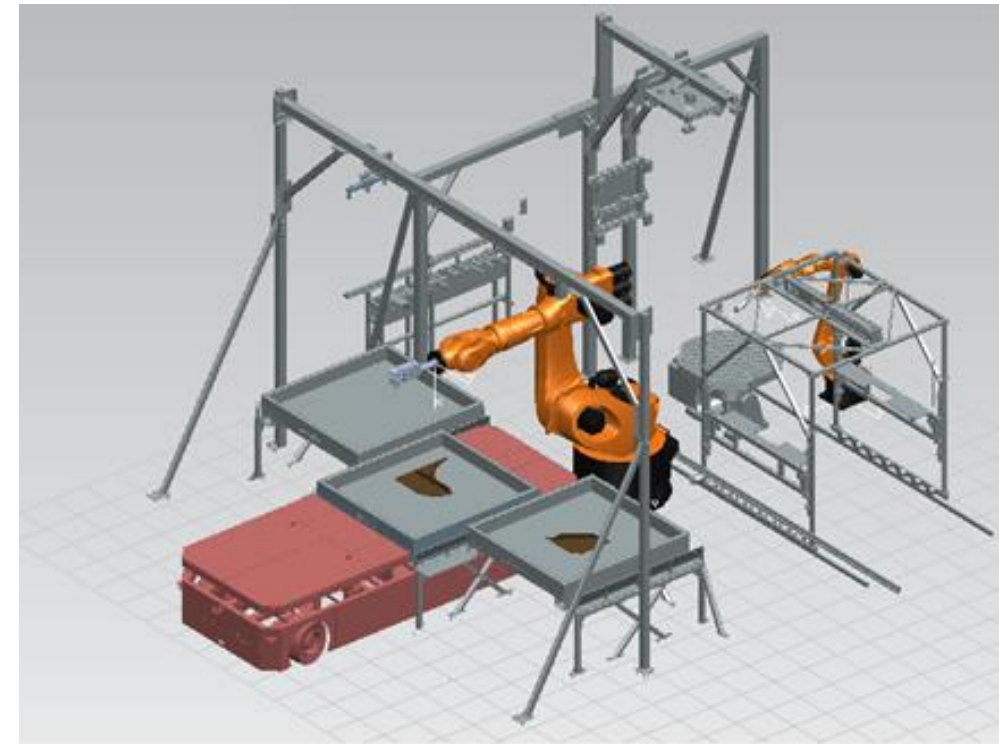
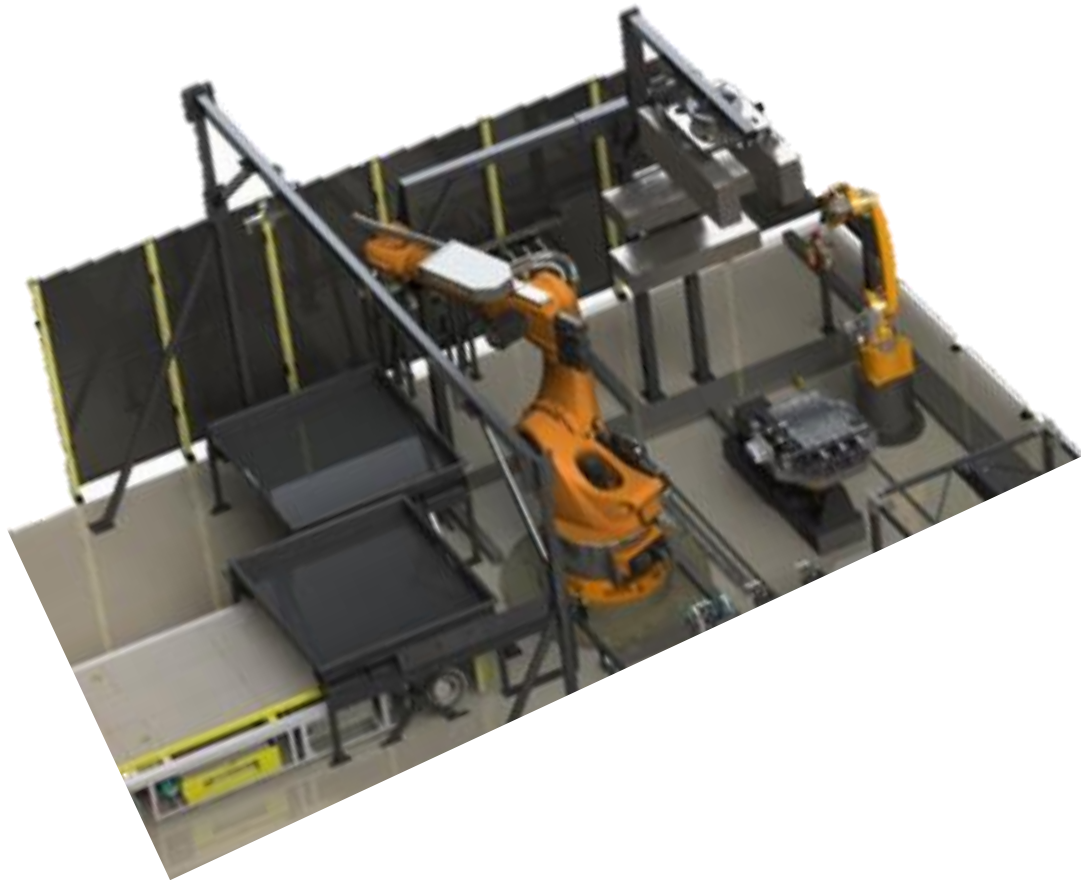
- Isolation
- Recovery

This leads to the very important subfield in the area of control systems called entitled "Fault detection, isolation, and recovery (FDIR)".

# Digital Twin research line CEMI (Navantia-UDC)

# Digital Twin research line CEMI (Navantia-UDC)

Minor preassemblies parts manufacturing cell



# Digital Twin research line CEMI (Navantia-UDC)

Minor preassemblies parts manufacturing cell



Transfer of materials into the welding cell



# Digital Twin research line CEMI (Navantia-UDC)

Minor preassemblies parts manufacturing cell

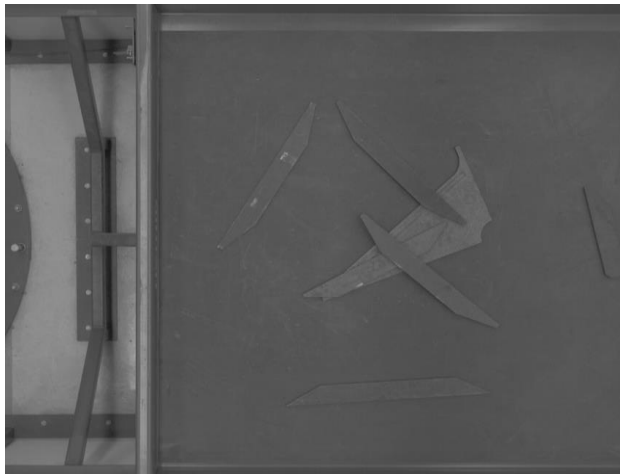


Artificial Vision Gantry

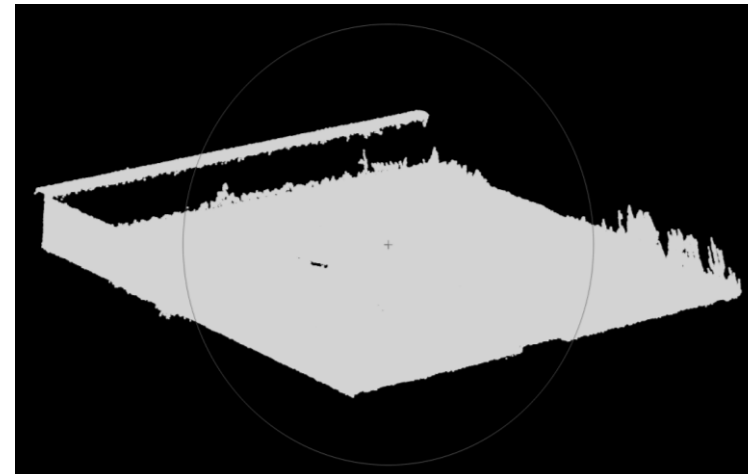
# Digital Twin research line CEMI (Navantia-UDC)

## Minor preassemblies parts manufacturing cell

3D camera



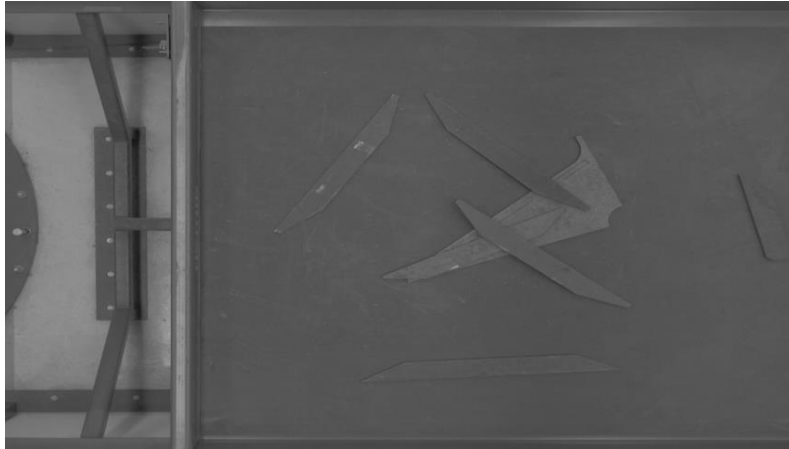
2D Image of the Tray



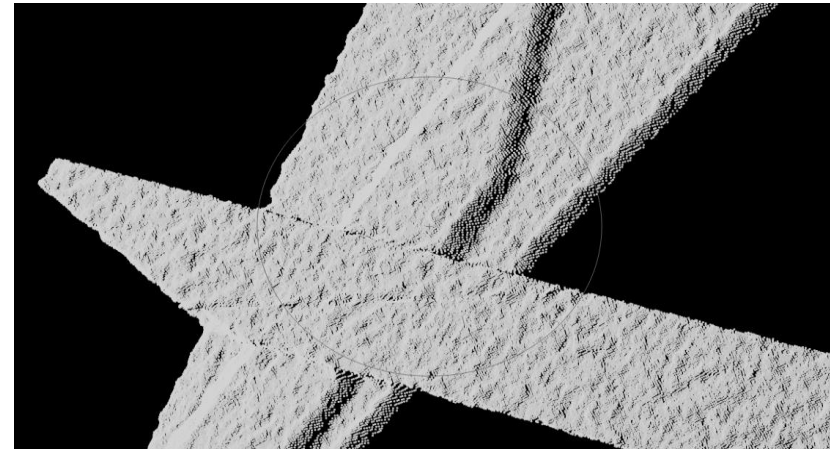
Point Cloud of the Tray

# Digital Twin research line CEMI (Navantia-UDC)

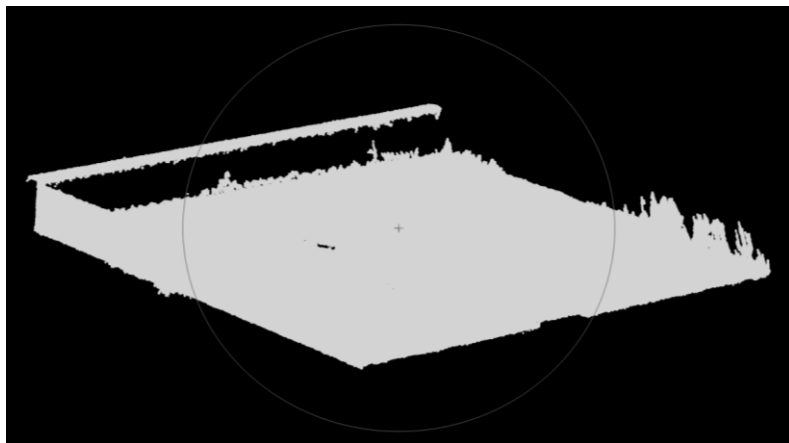
## Minor preassemblies parts manufacturing cell



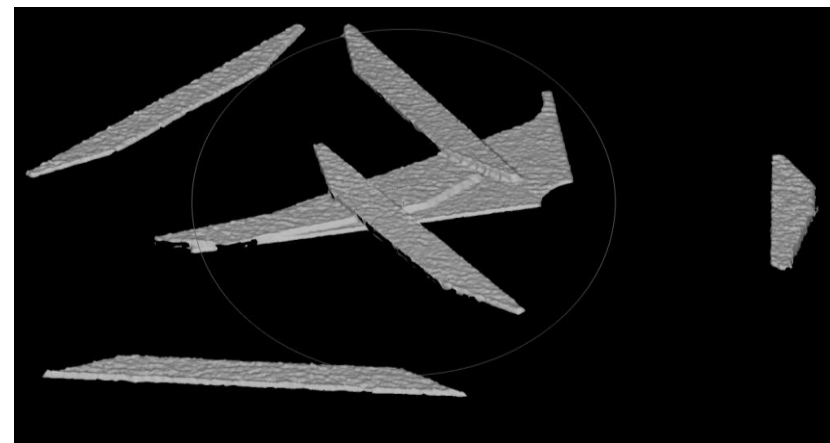
2D Monochromatic Image of the Tray



Zoom of the Processed Point cloud



Point Cloud of the Tray



Processed Point cloud of the elements in the tray

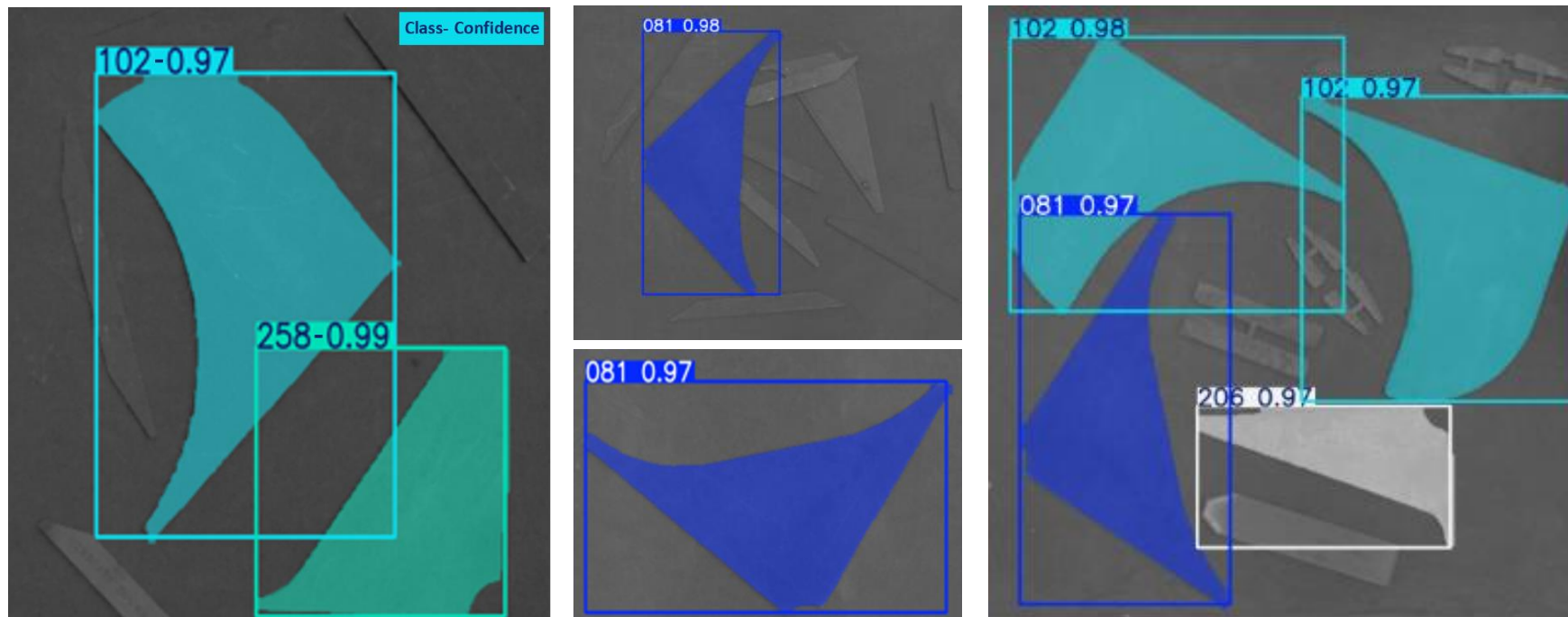
# Digital Twin research line CEMI (Navantia-UDC)

Minor preassemblies parts manufacturing cell

2D Techniques

⇒ Convolutional Neural Networks

⇒ Transformers



Instance  
Segmentation  
YOLOv8

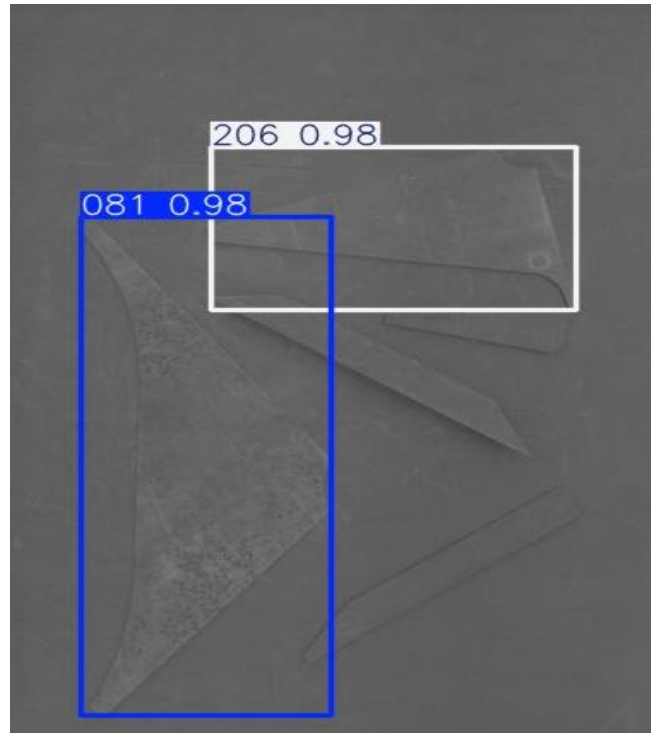
# Digital Twin research line CEMI (Navantia-UDC)

Minor preassemblies parts manufacturing cell

2D Techniques

⇒ Convolutional Neural Networks

⇒ Transformers



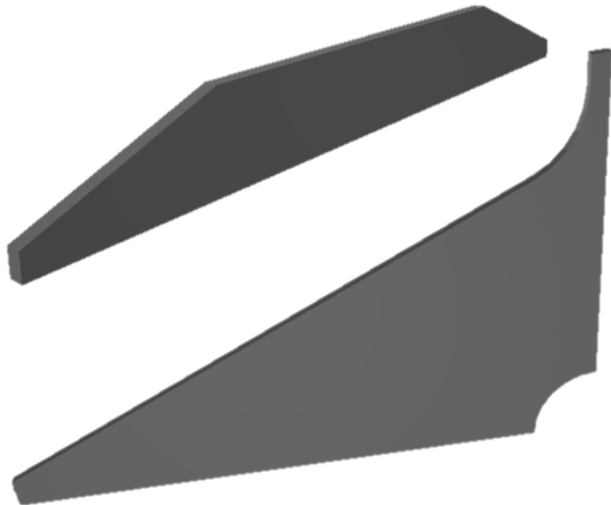
Object Detection  
RT-DETR

# Digital Twin research line CEMI (Navantia-UDC)

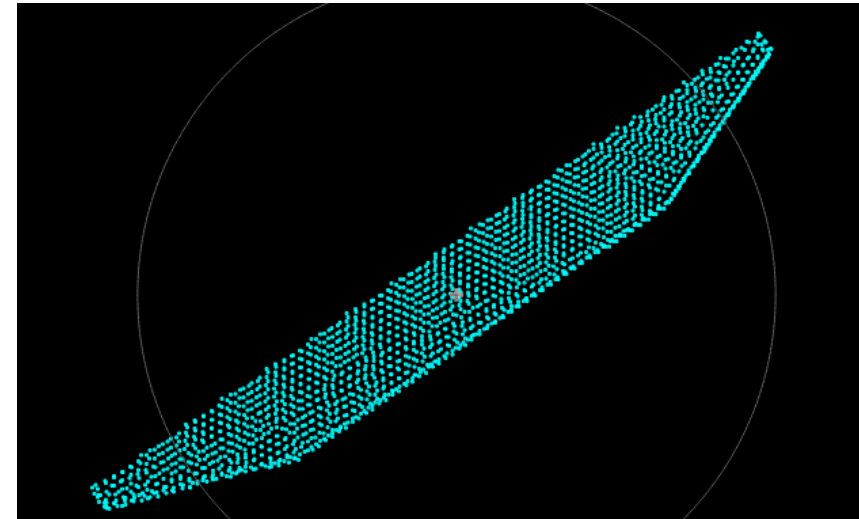
Minor preassemblies parts manufacturing cell

## 3D Techniques

- ⇒ Surface Matching
- ⇒ 3D Edge Matching



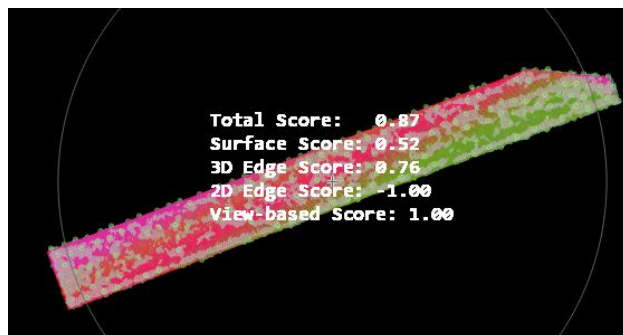
CAD Models



Surface model

# Digital Twin research line CEMI (Navantia-UDC)

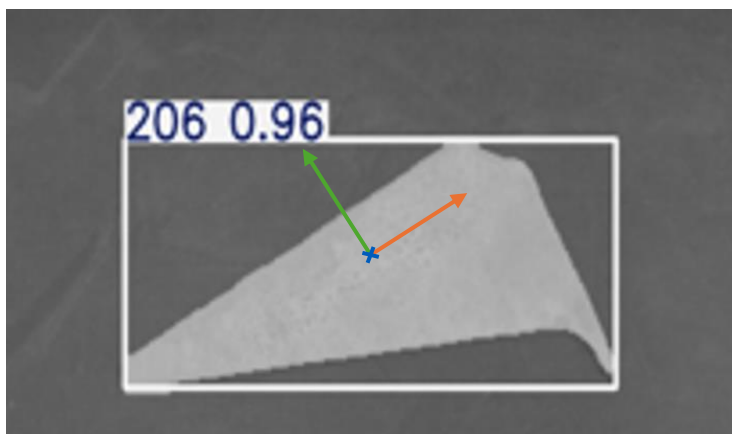
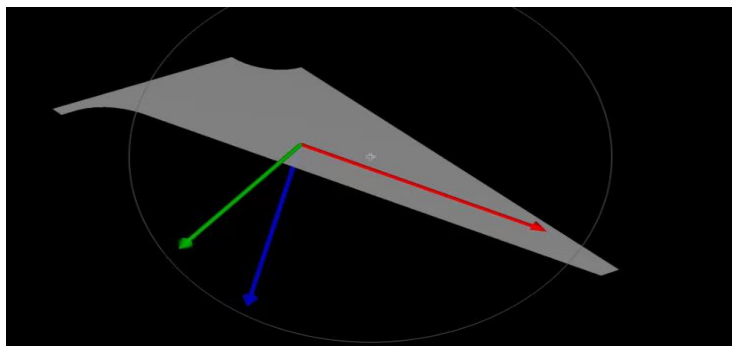
## Minor preassemblies parts manufacturing cell



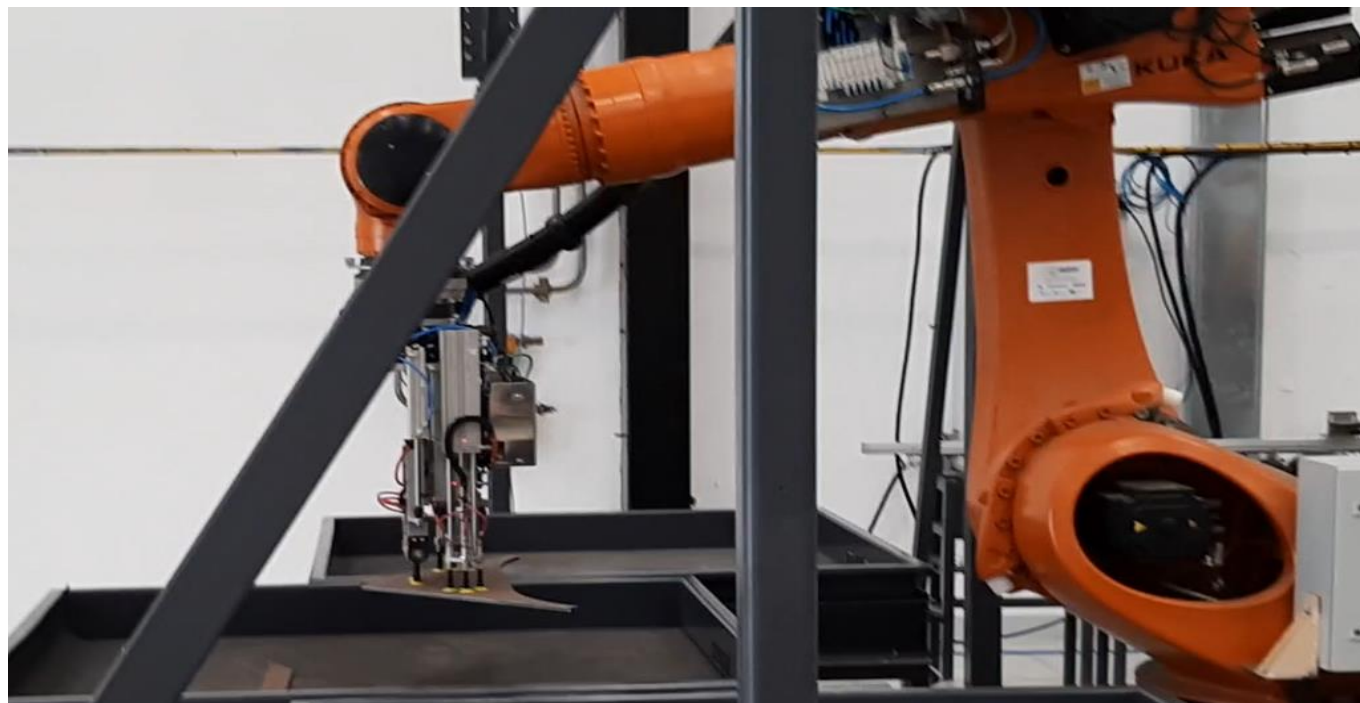
### Matching Results

# Digital Twin research line CEMI (Navantia-UDC)

Minor preassemblies parts manufacturing cell



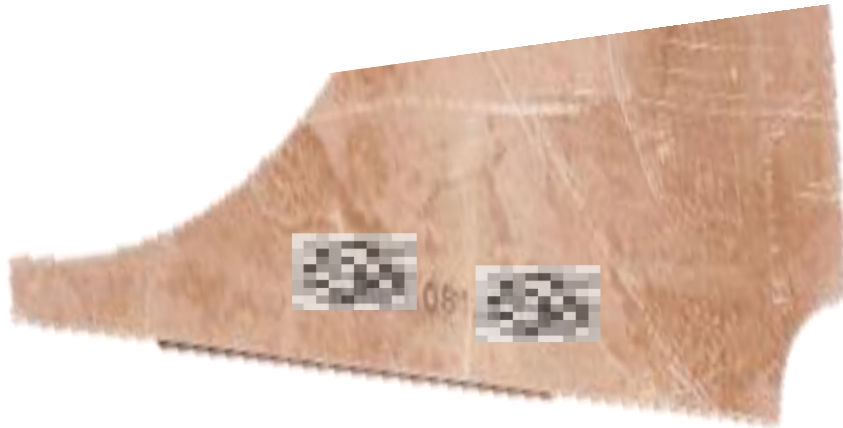
Orientation of the pieces



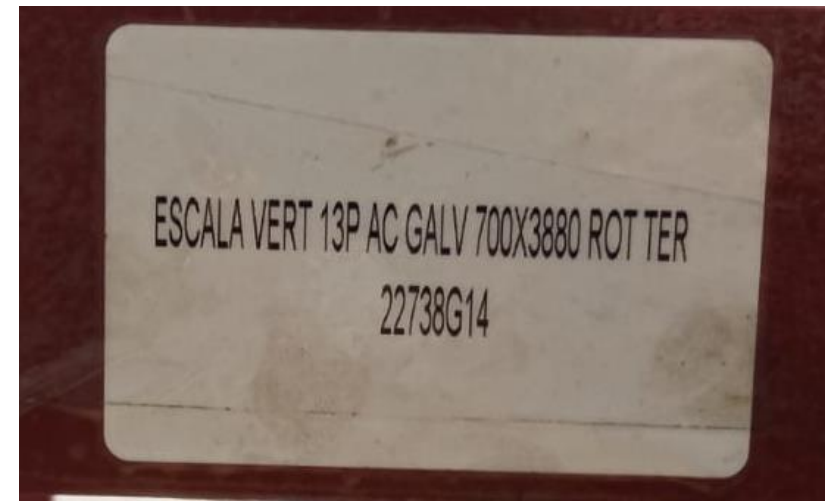


# Digital Twin research line CEMI (Navantia-UDC)

Minor preassemblies parts manufacturing cell



Optical Character  
Recognition



# Digital Twin research line CEMI (Navantia-UDC)

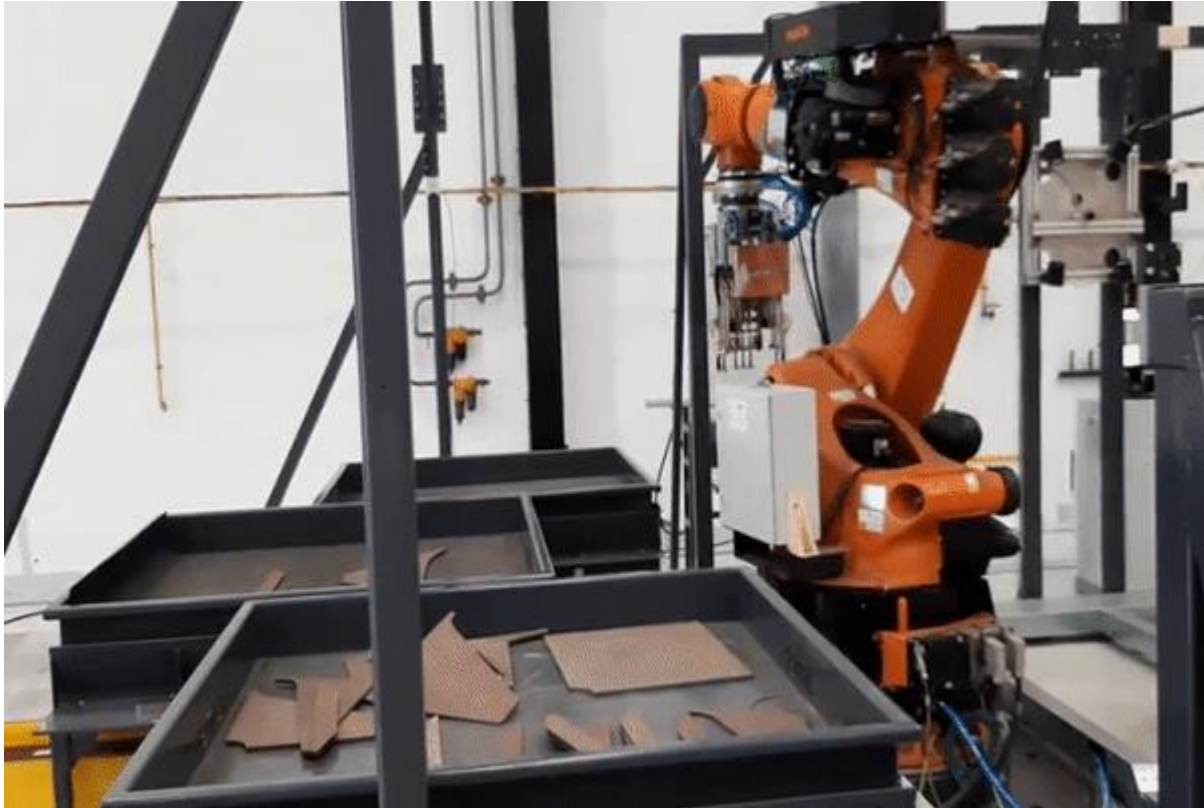
Minor preassemblies parts manufacturing cell



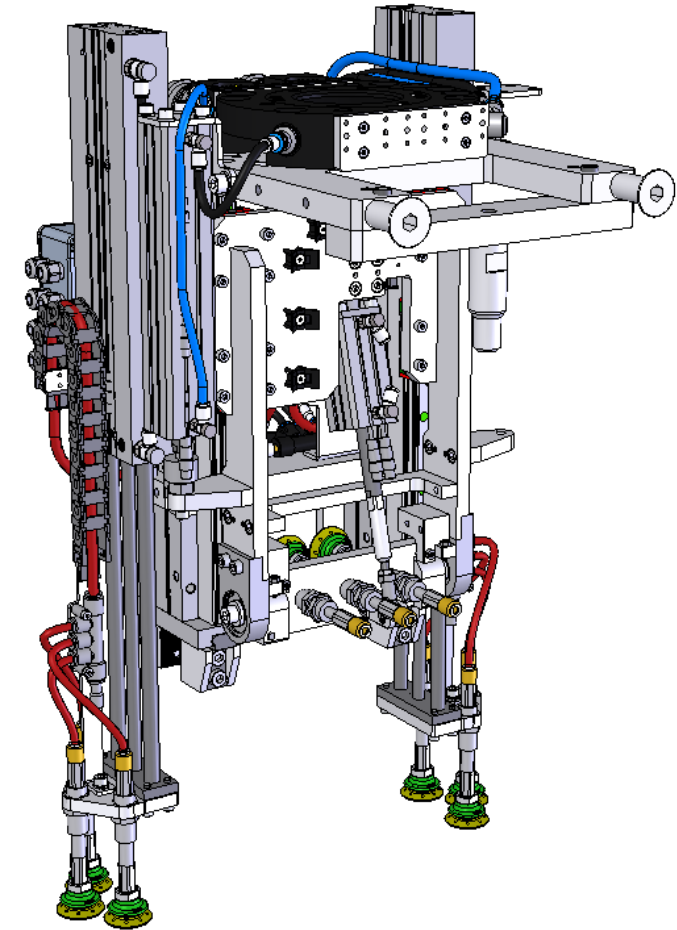
Defect detection

# Digital Twin research line CEMI (Navantia-UDC)

Minor preassemblies parts manufacturing cell

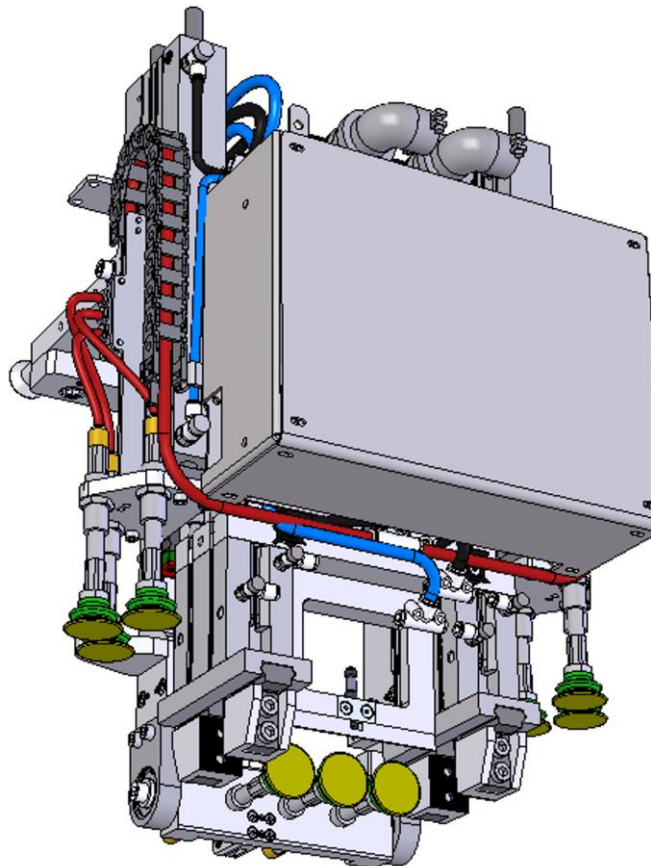
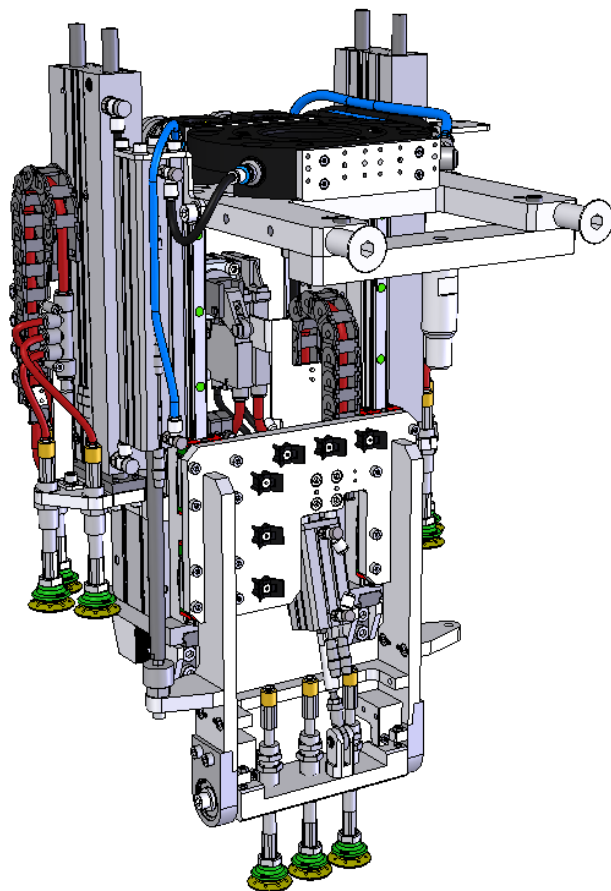


Base plates pick up



# Digital Twin research line CEMI (Navantia-UDC)

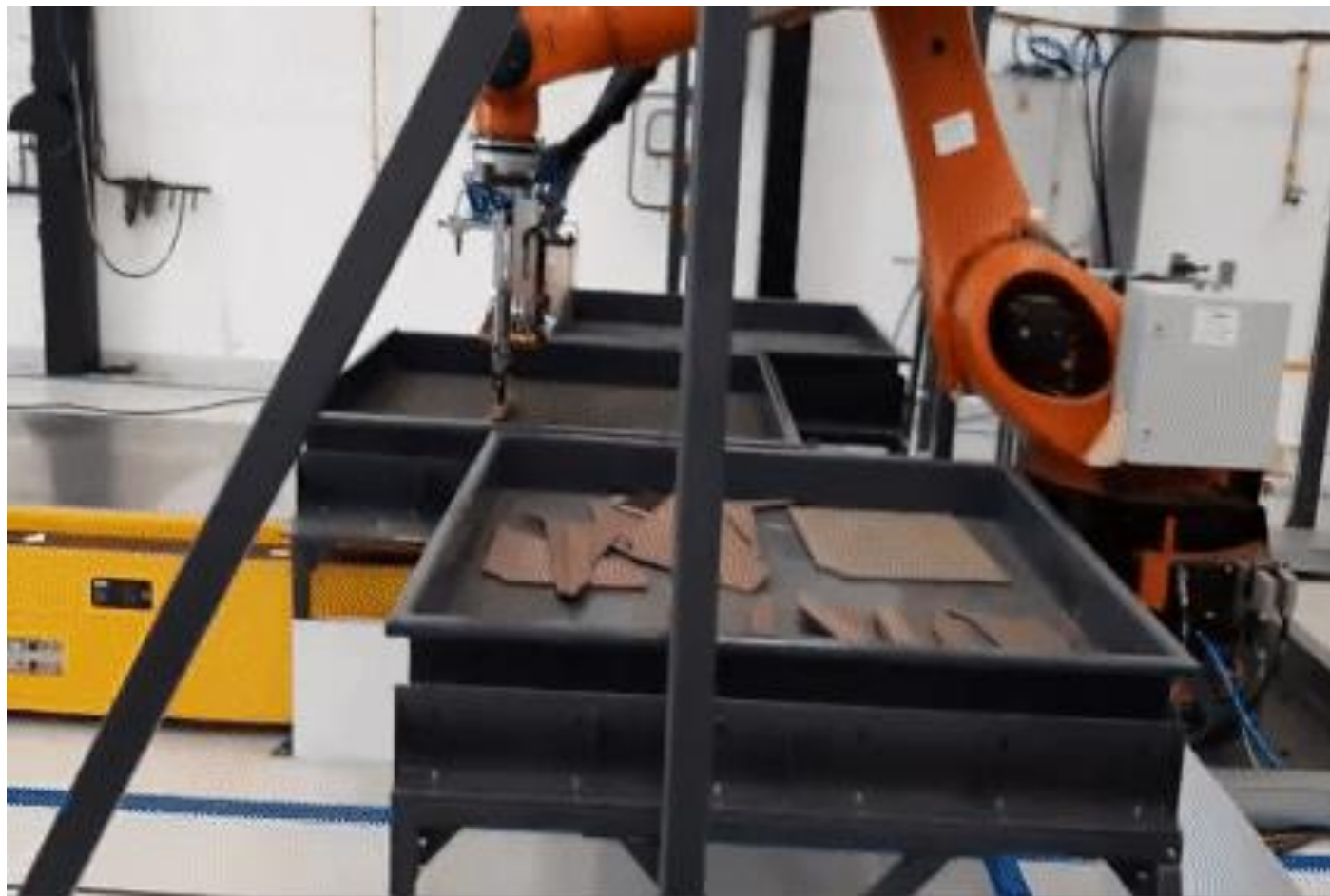
Minor preassemblies parts manufacturing cell



Reinforcements pick up

# Digital Twin research line CEMI (Navantia-UDC)

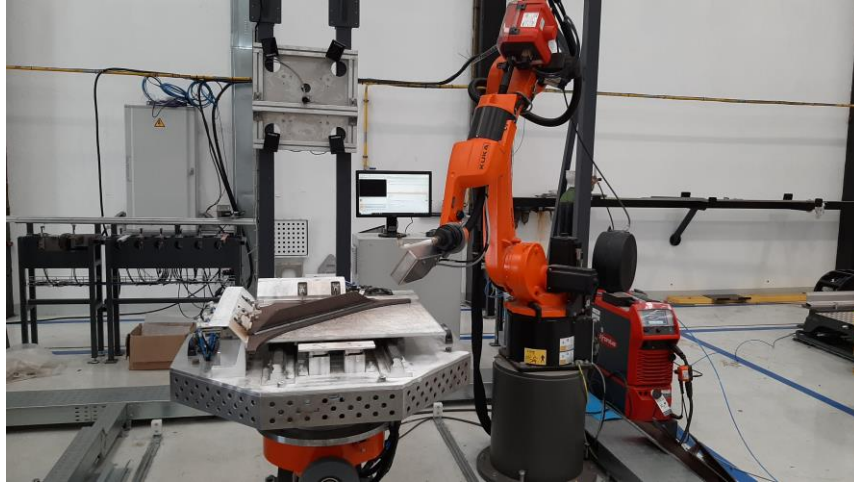
Minor preassemblies parts manufacturing cell



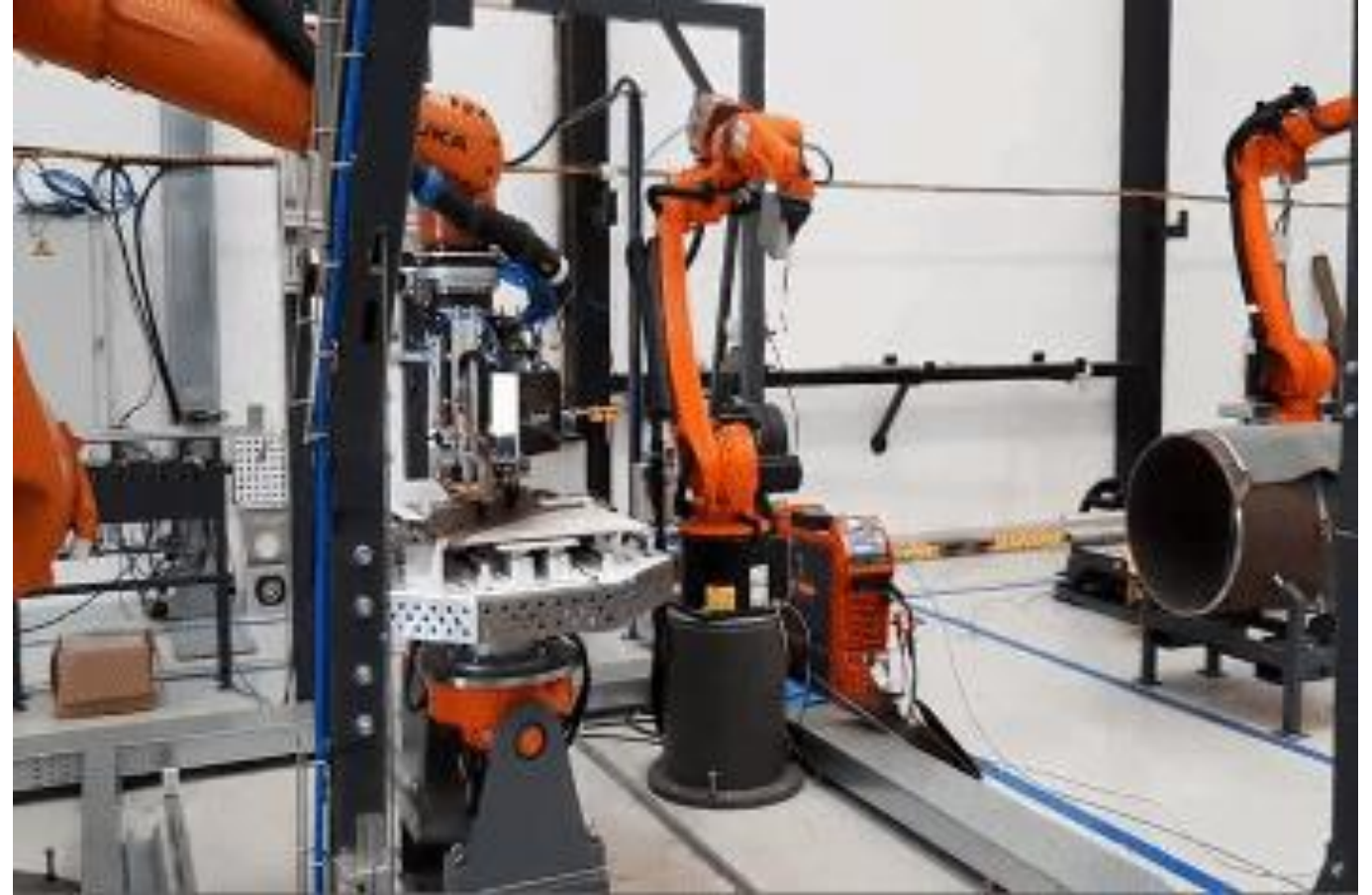
Reinforcements pick up

# Digital Twin research line CEMI (Navantia-UDC)

Minor preassemblies parts manufacturing cell



Application of traditional/intelligent techniques for the detection of failures or anomalies in welding

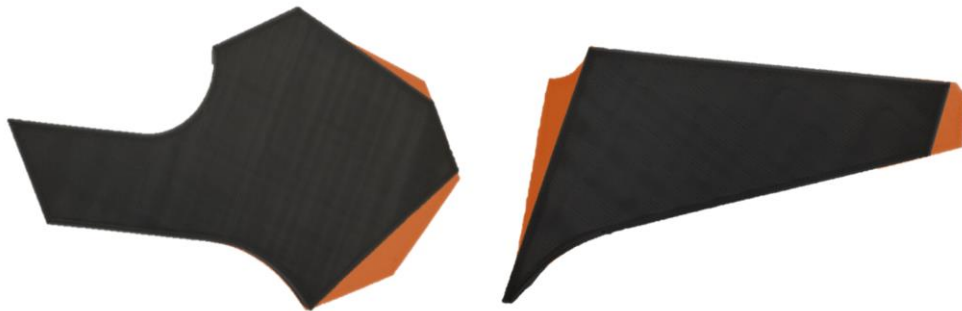


# Digital Twin research line CEMI (Navantia-UDC)

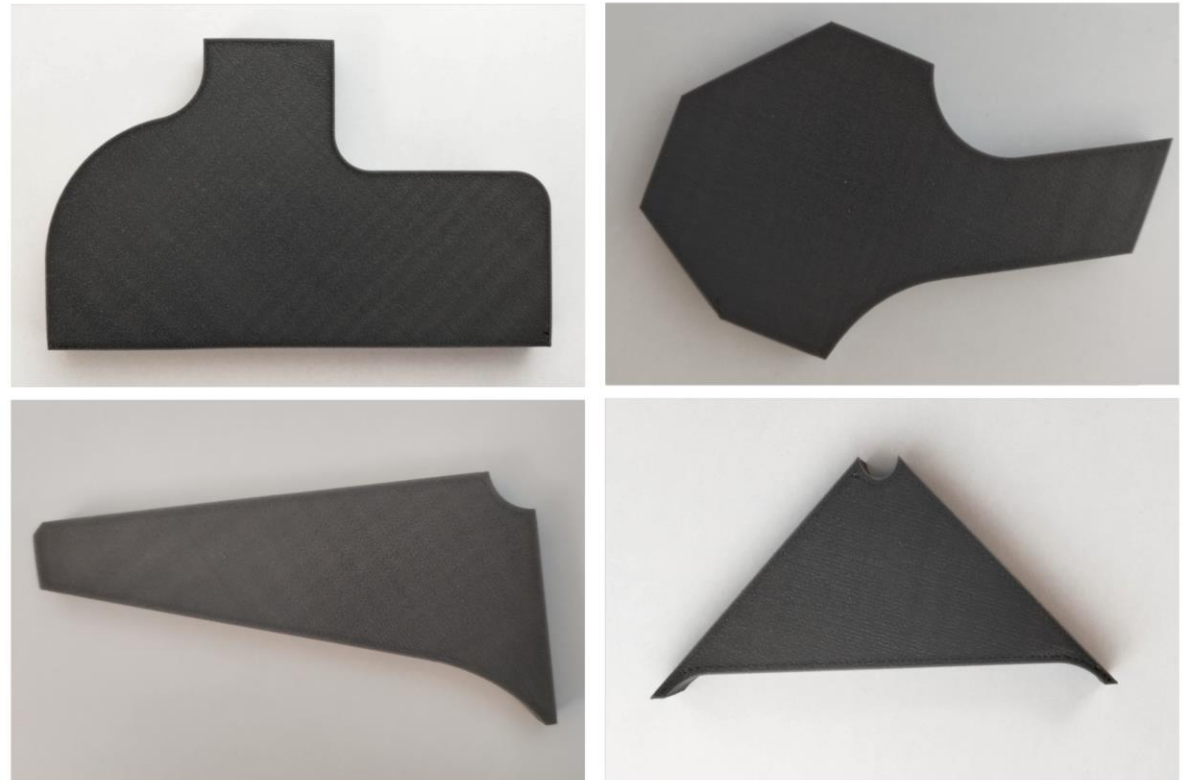
Laboratory tests (Due to Navantia confidentiality)



Intel RealSense D455 Depth Camera



Defective Piece with Highlighted Defects in Orange



Images of the four different 3D printed pieces.

# Our proposals for Fault Detection accomplishing



# Our proposals for Fault Detection accomplishing

## Techniques and implementation

What kind of FD techniques we use:

- Traditional ones based on statistical methods
- Based on intelligent techniques

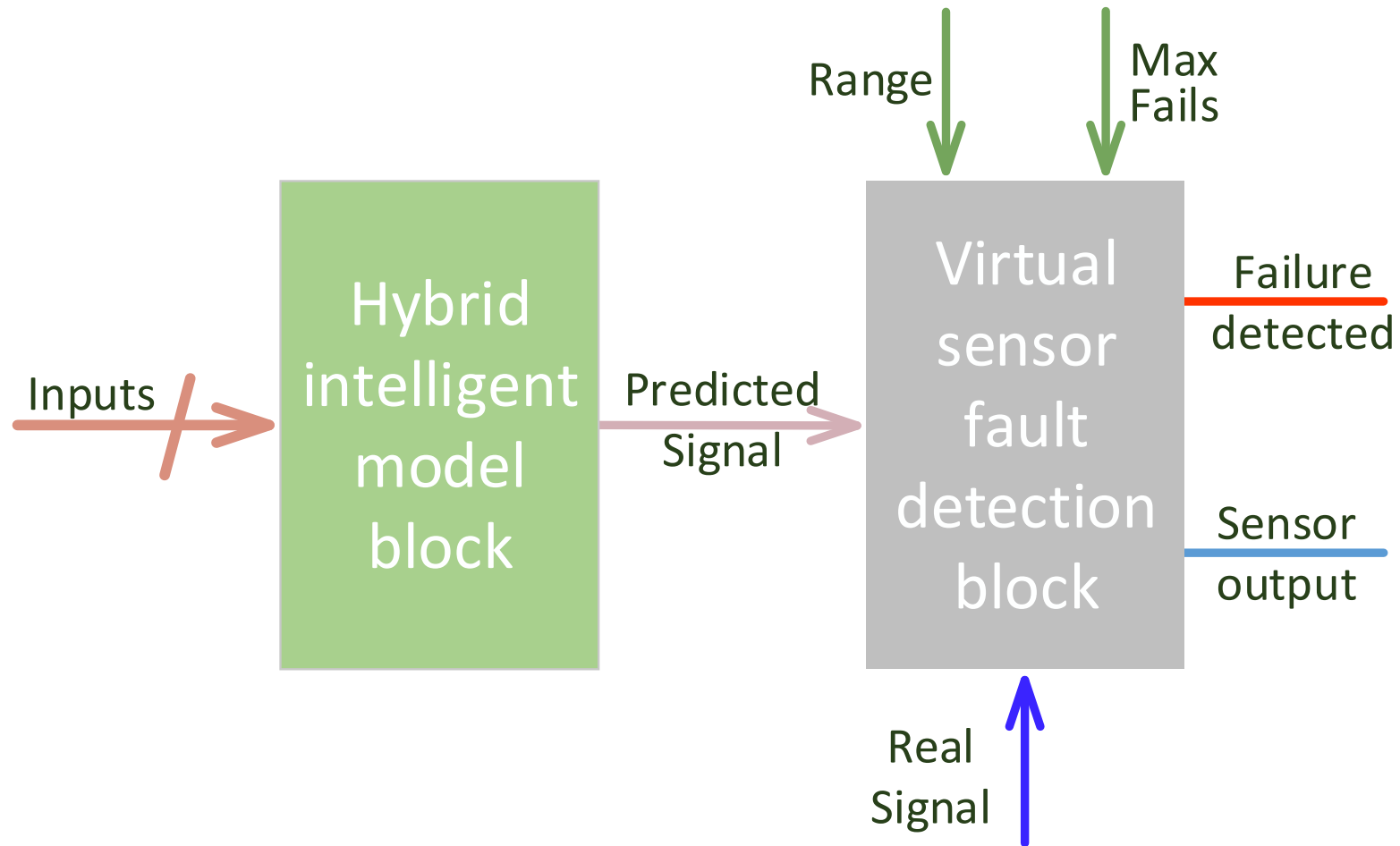
The implementation attending to the topology:

- Based on models
- Based on One-class techniques

# Based on model

# Based on model

Anomaly detection based on virtual sensors

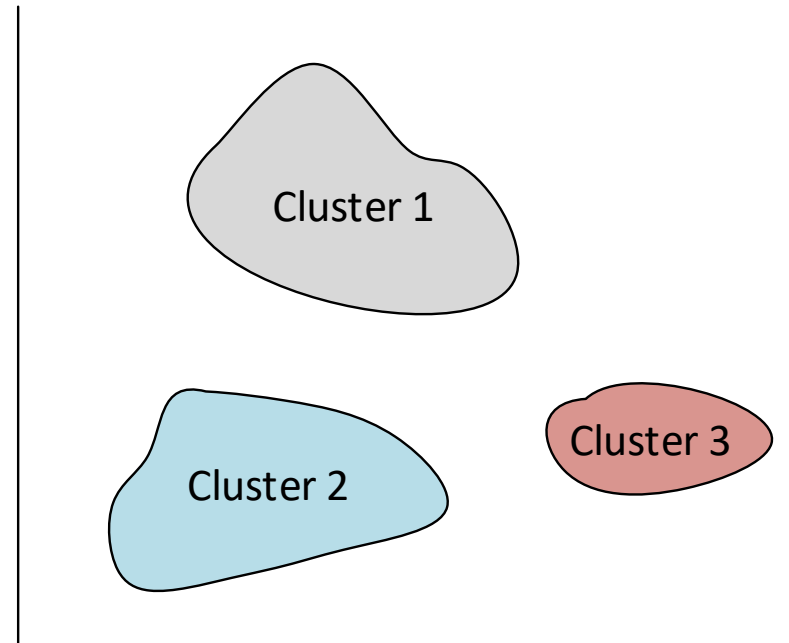


## Based on model

Anomaly detection based on virtual sensors

### Hybrid intelligent model block.

- Modeling process.

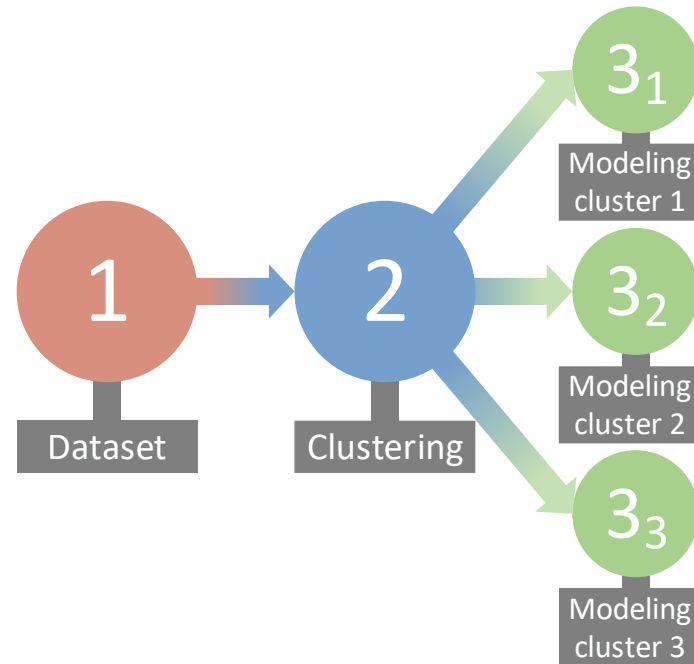


## Based on model

Anomaly detection based on virtual sensors

### Hybrid intelligent model block.

- Modeling process.

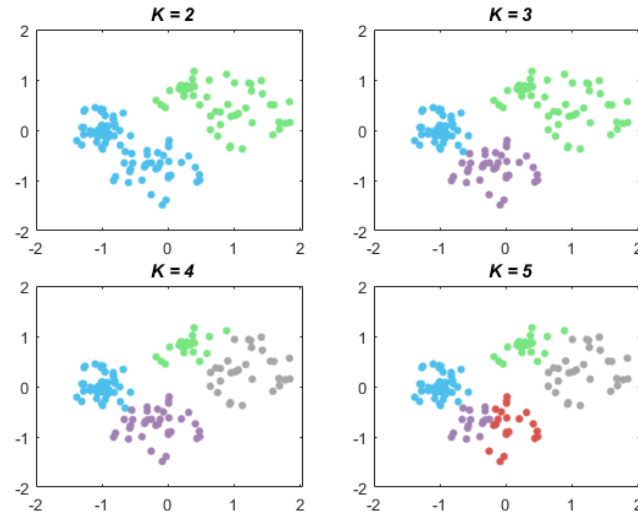


# Based on model

Anomaly detection based on virtual sensors

## Hybrid intelligent model block.

- Modeling process → Clustering → Kmeans



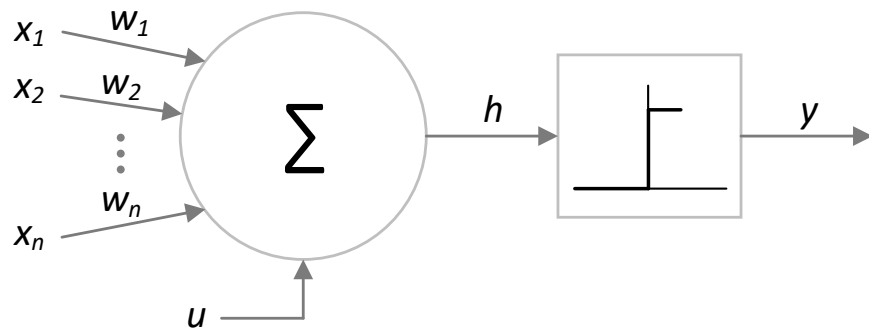
$$E(c_1, \dots, c_K) = \sum_{i=1}^N \sum_{j=1}^K I(x_i \in G_j) \|x_i - c_j\|$$

# Based on model

Anomaly detection based on virtual sensors

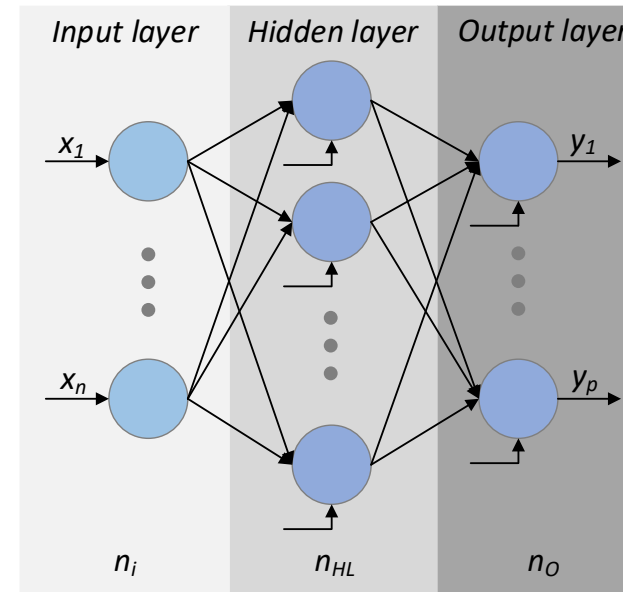
## Hybrid intelligent model block.

- Modeling process → Modeling → MLP



$$h = f_{\theta_1}(xW_1 - u_1)$$

$$y = f_{\theta_2}(hW_2 - u_2)$$

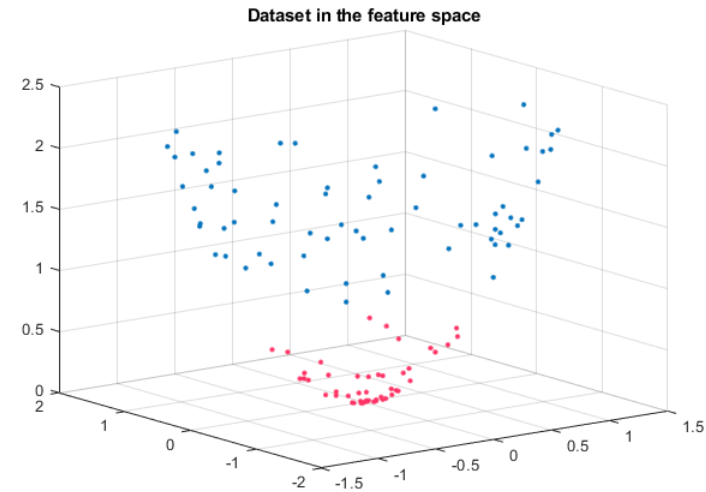
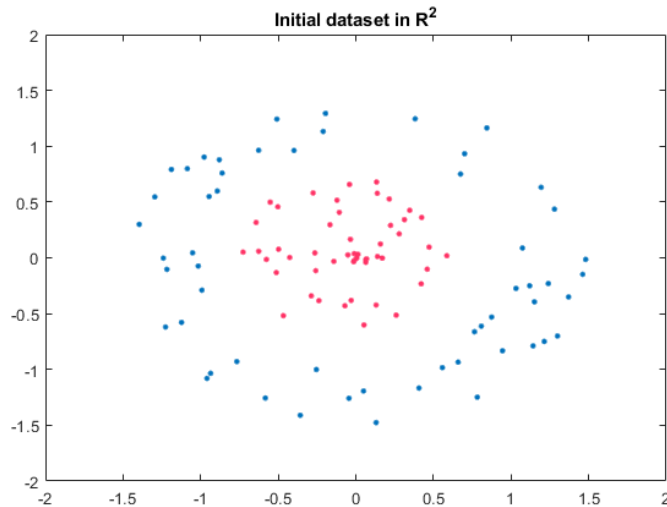


# Based on model

Anomaly detection based on virtual sensors

## Hybrid intelligent model block.

- Modeling process → Modeling → LS SVR



$$y = f(X) = w^T \delta(x) + b$$

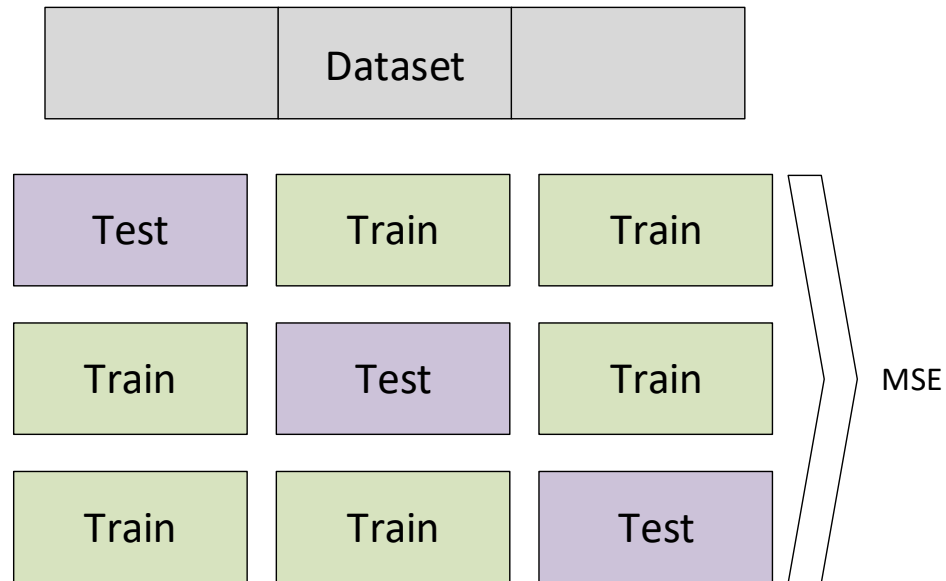


# Based on model

Anomaly detection based on virtual sensors

## Hybrid intelligent model block.

- Modeling process → Modeling → Validation

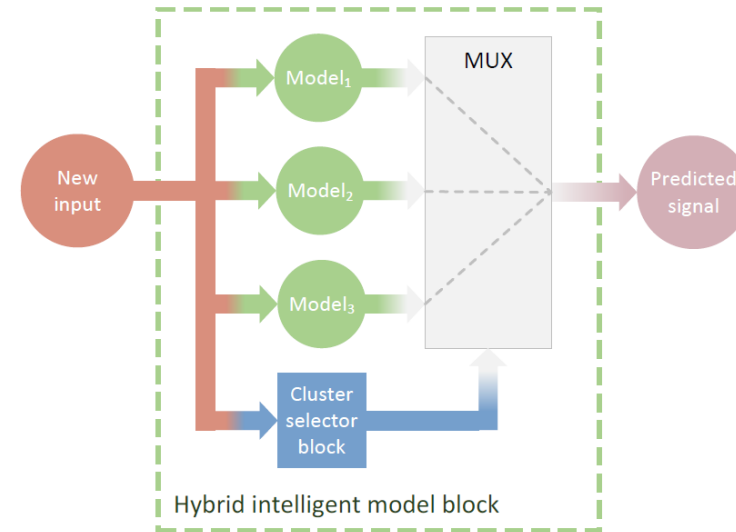
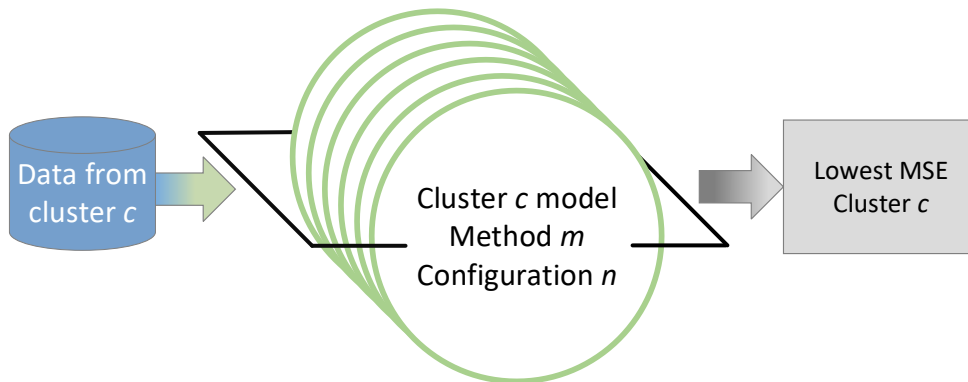


# Based on model

Anomaly detection based on virtual sensors

## Hybrid intelligent model block.

- Modeling process → Modeling → Best configuration

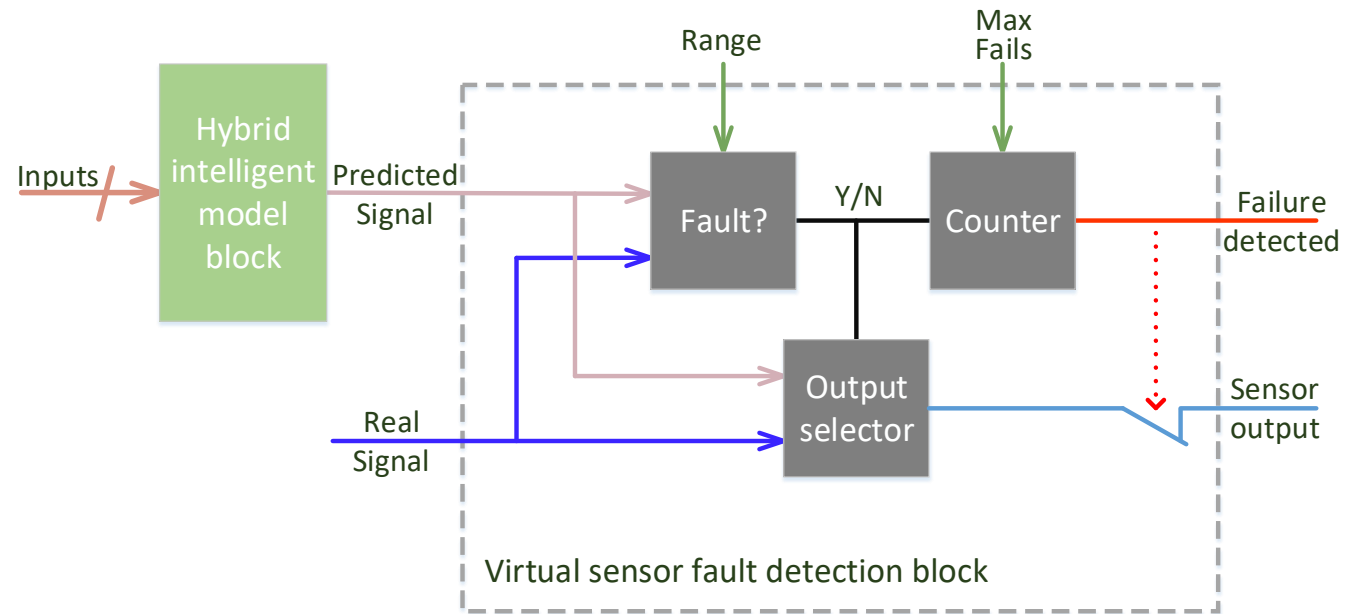


# Based on model

Anomaly detection based on virtual sensors

## Virtual sensor fault detection block.

- Virtual sensor fault detection block → Fault block

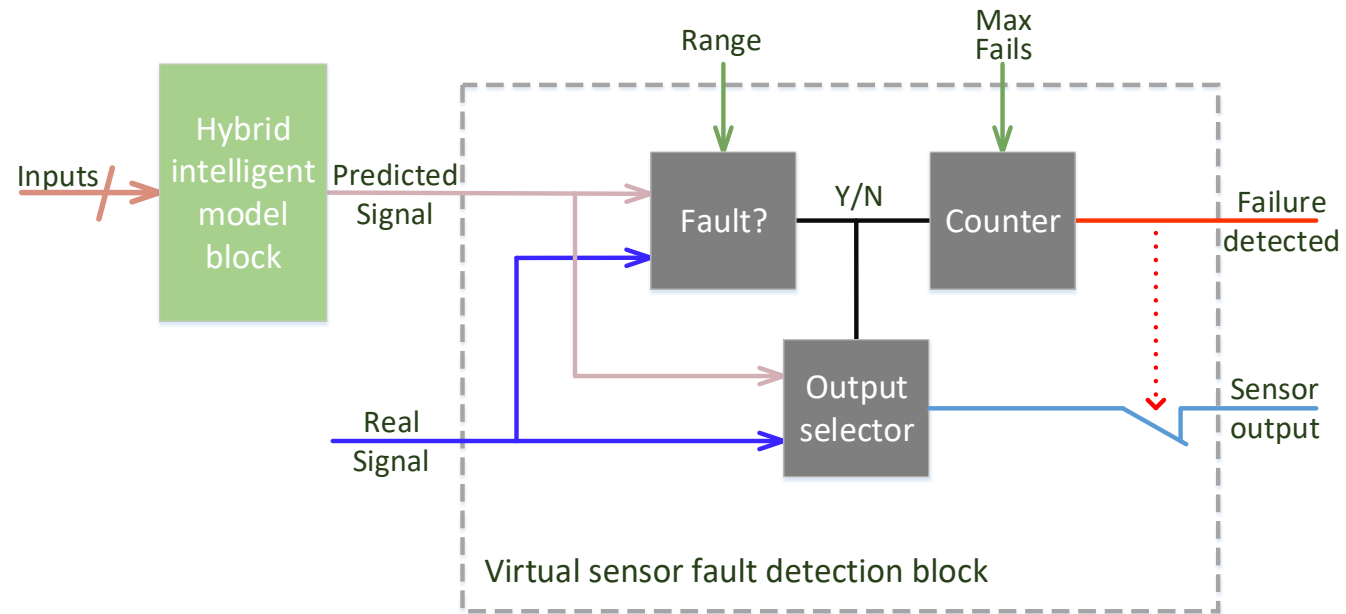


# Based on model

Anomaly detection based on virtual sensors

## Virtual sensor fault detection block.

- Virtual sensor fault detection block → Counter block

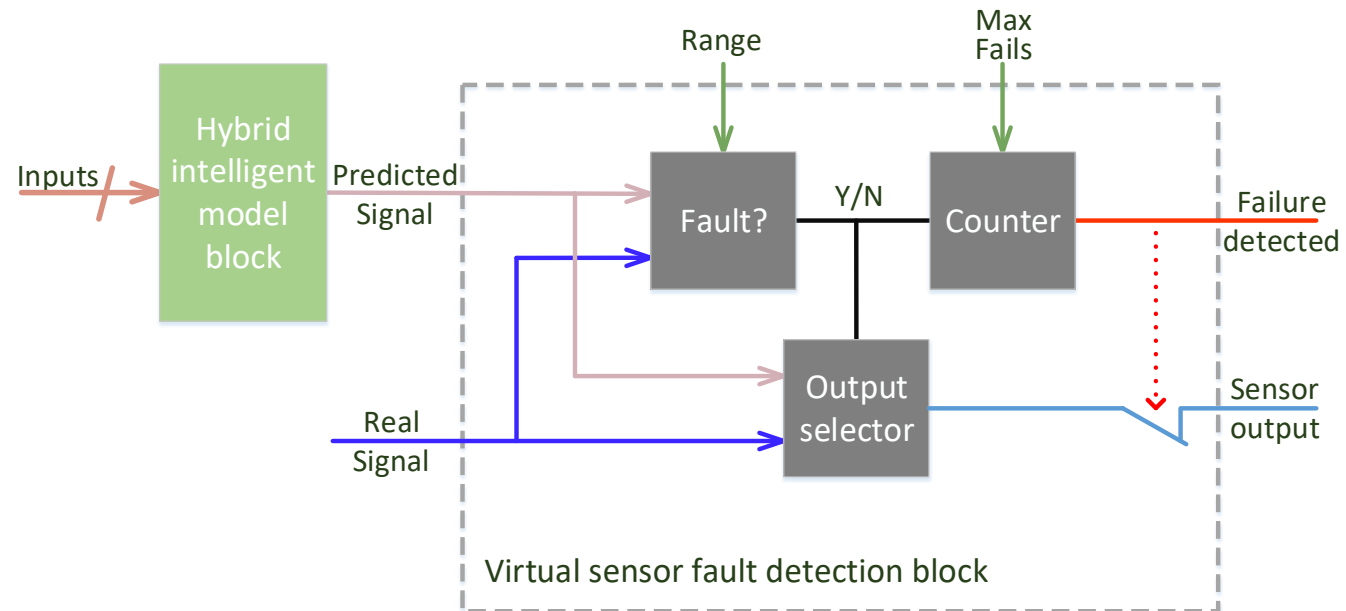


# Based on model

Anomaly detection based on virtual sensors

## Virtual sensor fault detection block.

- Virtual sensor fault detection block → Output selector block

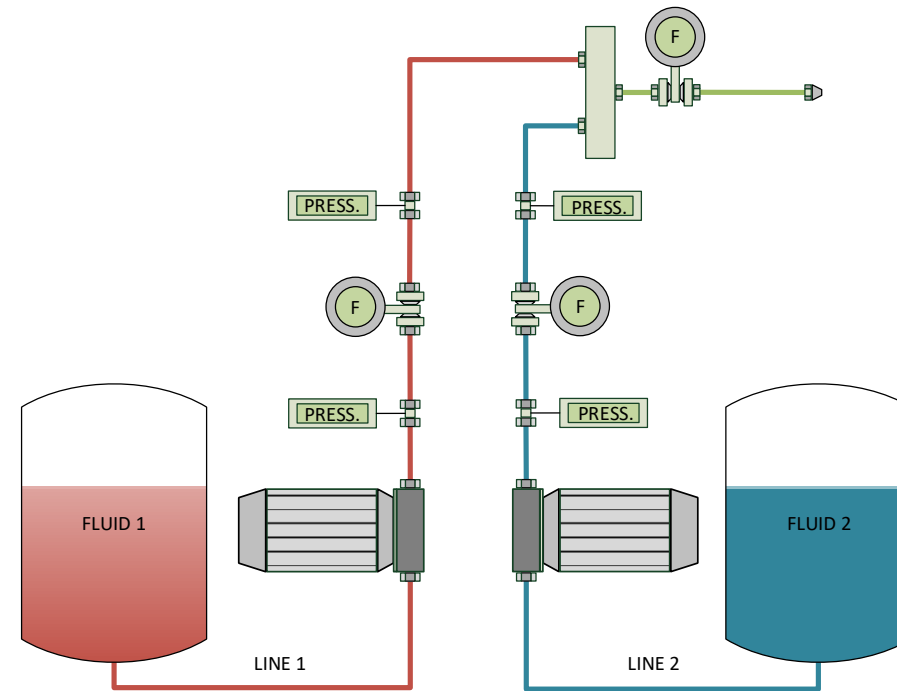


# Based on model

Anomaly detection based on virtual sensors

## Bicomponent mixing system → Real case of application

- Virtual sensor for fault detection, isolation and data recovery for bicomponent mixing machine monitoring

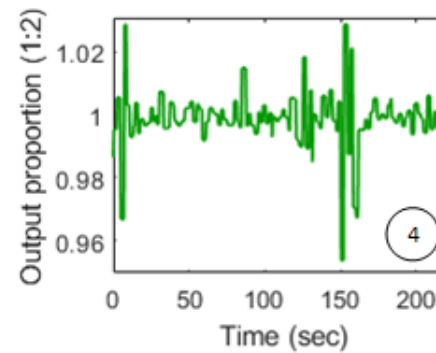
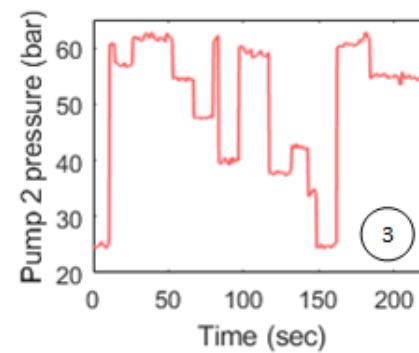
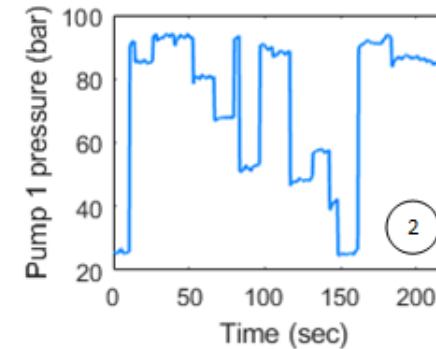
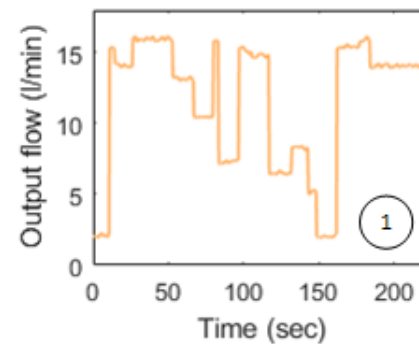
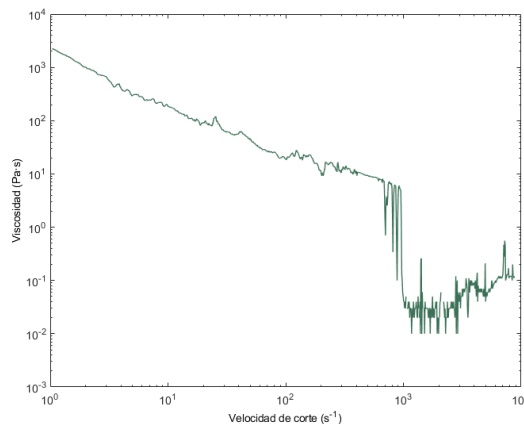


# Based on model

Anomaly detection based on virtual sensors

## Bicomponent mixing system

- Monitored variables.
  - Mixing proportions.
  - Two pump speeds.
  - Three flows.
  - Four pressures.
- Dataset: 8549 samples.



## Based on model

Anomaly detection based on virtual sensors

### Bicomponent mixing system

- Experiments and results.
  - Model inputs.
    - Output flow, Flow 2 (t, t-1, t-2).
    - Pumps pressures 1 and 2 (t, t-1, t-2).
    - Flowmeters pressures 1 and 2 (t, t-1, t-2).
    - Flow 1 (t-1, t-2).
  - Model Output.
    - Flow 1 (t).
  - Techniques
    - Kmeans → Clusters: 1:1:10.
    - MLP → Hidden layer neurons: 1:1:15 / Different activation functions.
    - LS-SVR → Self-tuned optimization toolbox.



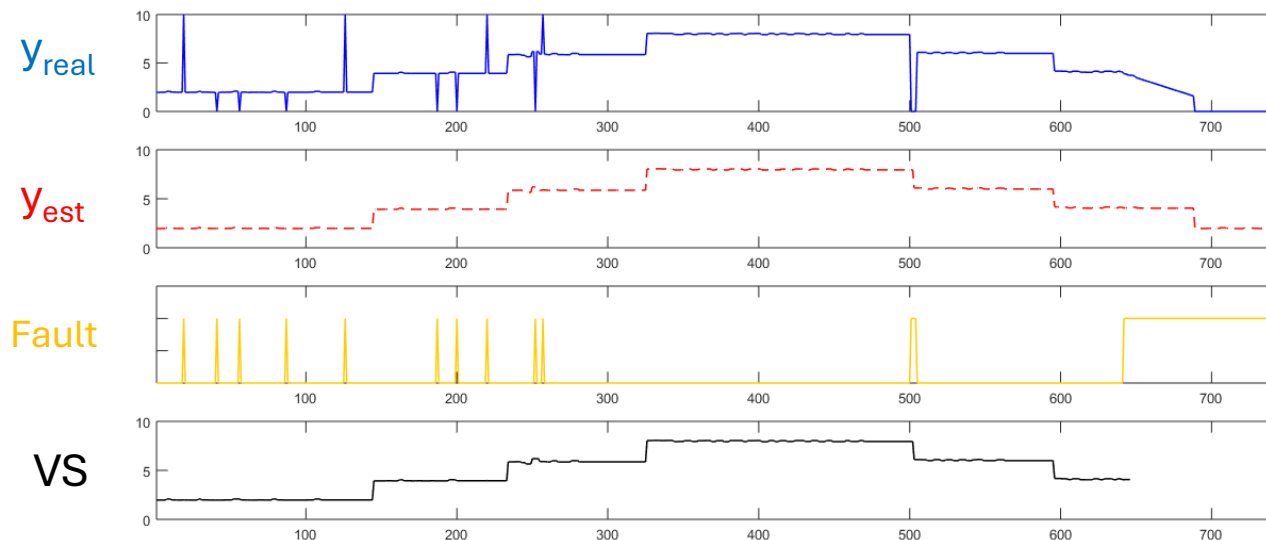
# Based on model

Anomaly detection based on virtual sensors

## Bicomponent mixing system

- Experiments and results.
  - Best configuration.
    - 7 clusters.
    - MSE =  $0,131 \cdot 10^{-3}$ .

	Cluster 1	Cluster 2	Cluster 3	Cluster 4	Cluster 5	Cluster 6	Cluster 7
Technique	ANN-1	ANN-1	ANN-7	ANN-5	ANN-3	ANN-3	ANN-8
MSE	$0.165 \cdot 10^{-3}$	$0.159 \cdot 10^{-3}$	$0.097 \cdot 10^{-3}$	$0.55 \cdot 10^{-3}$	$0.183 \cdot 10^{-3}$	$0.163 \cdot 10^{-3}$	$0.122 \cdot 10^{-3}$



# Based on One-class techniques

# Based on One-class techniques

Anomaly detection based on One-class techniques

## Fundamentals

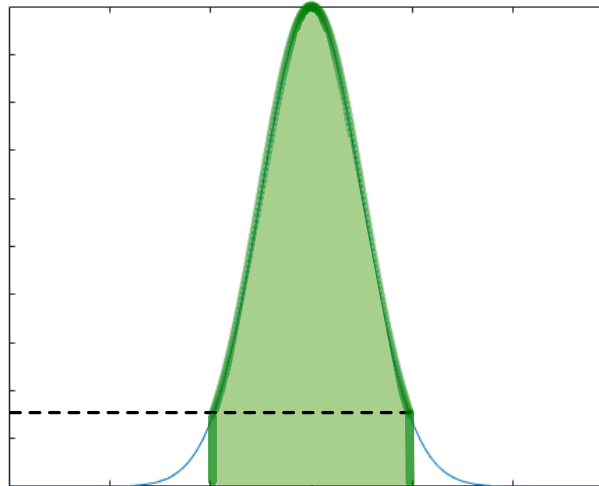
- One-class:
  - Density estimation methods.
  - Reconstruction methods.
  - Boundary methods.

# Based on One-class techniques

Anomaly detection based on One-class techniques

## Fundamentals

- One-class:
  - **Density estimation methods.**
  - Reconstruction methods.
  - Boundary methods.

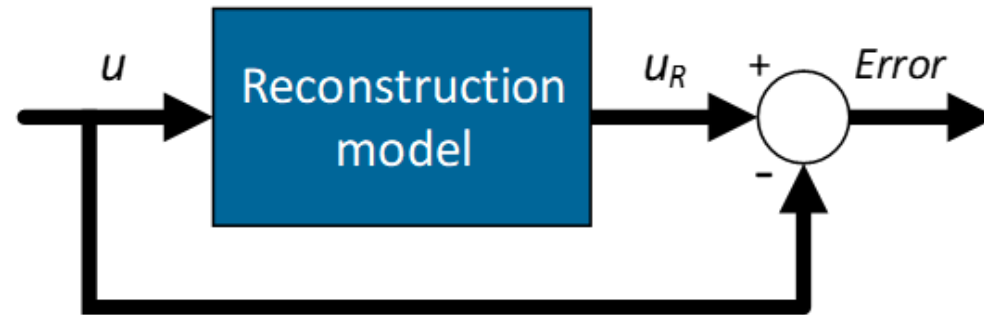


# Based on One-class techniques

Anomaly detection based on One-class techniques

## Fundamentals

- One-class:
  - Density estimation methods.
  - **Reconstruction methods.**
  - Boundary methods.

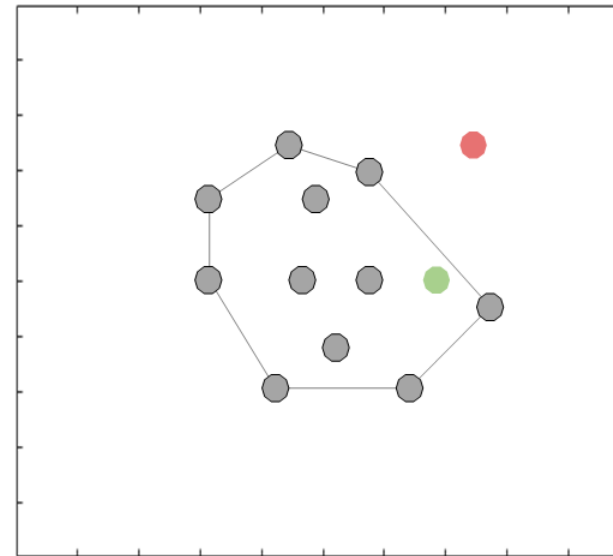


# Based on One-class techniques

Anomaly detection based on One-class techniques

## Fundamentals

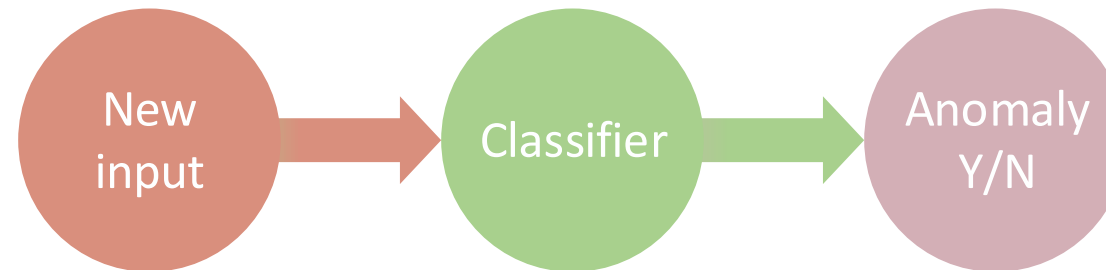
- One-class:
  - Density estimation methods.
  - Reconstruction methods.
  - **Boundary methods.**



# Based on One-class techniques

Anomaly detection based on One-class techniques

## Fundamentals

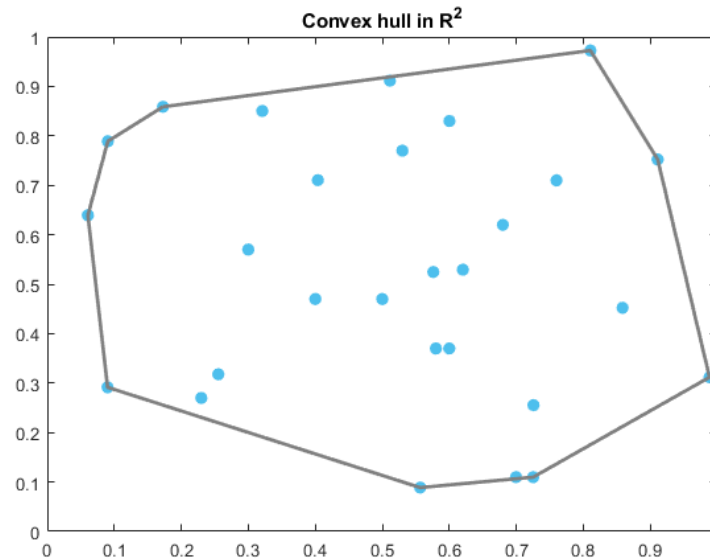


# Based on One-class techniques

Anomaly detection based on One-class techniques

## Implementation

- One-class techniques.
  - ACH.



$$CH(X) = \left\{ \sum_{i=1}^N \alpha_i x_i \mid \sum_{i=1}^N \alpha_i = 1, 0 \leq \alpha_i \leq 1 \right\}$$

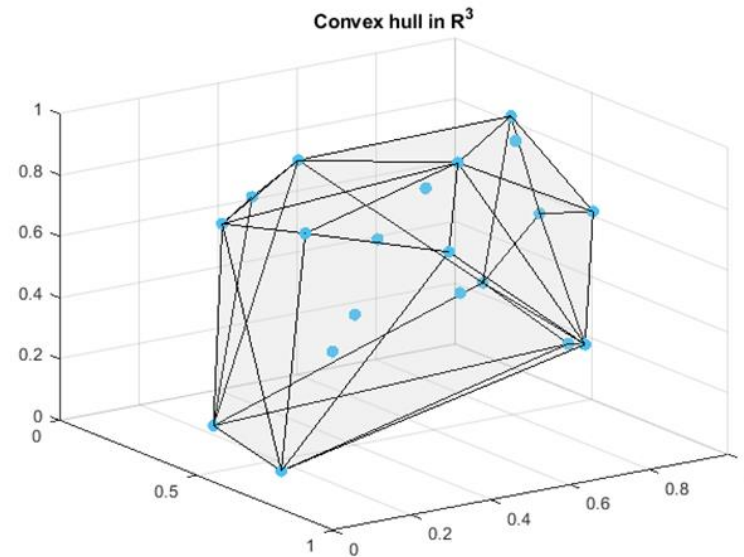


# Based on One-class techniques

Anomaly detection based on One-class techniques

## Implementation

- One-class techniques.
  - ACH.



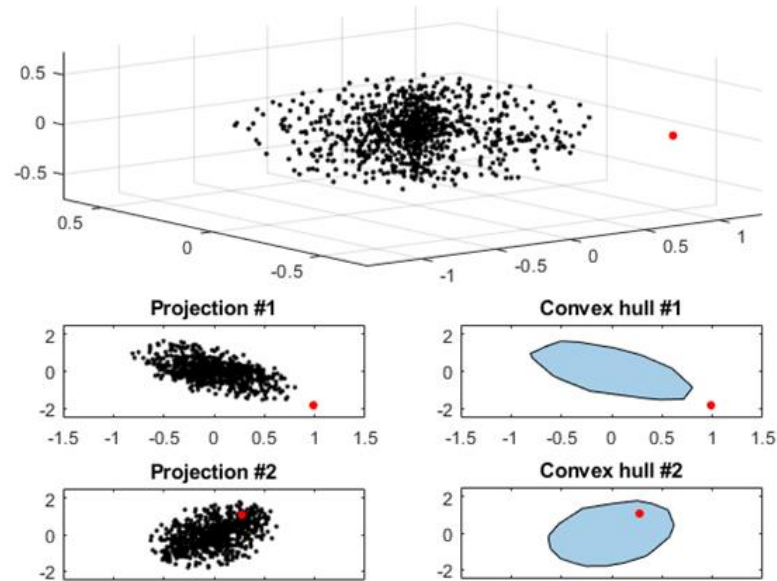
$$CH(X) = \left\{ \sum_{i=1}^N \alpha_i x_i \mid \sum_{i=1}^N \alpha_i = 1, 0 \leq \alpha_i \leq 1 \right\}$$

# Based on One-class techniques

Anomaly detection based on One-class techniques

## Implementation

- One-class techniques.
  - ACH.



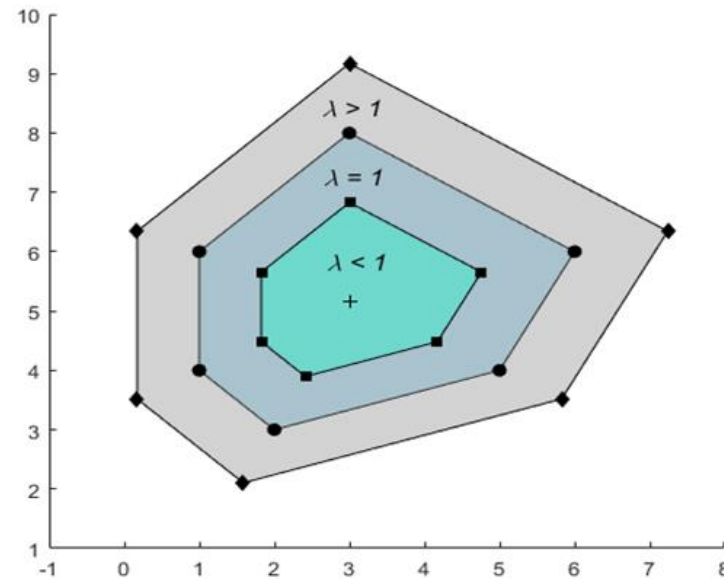
$$CH(X) = \left\{ \sum_{i=1}^N \alpha_i x_i \mid \sum_{i=1}^N \alpha_i = 1, 0 \leq \alpha_i \leq 1 \right\}$$

# Based on One-class techniques

Anomaly detection based on One-class techniques

## Implementation

- One-class techniques.
  - ACH.



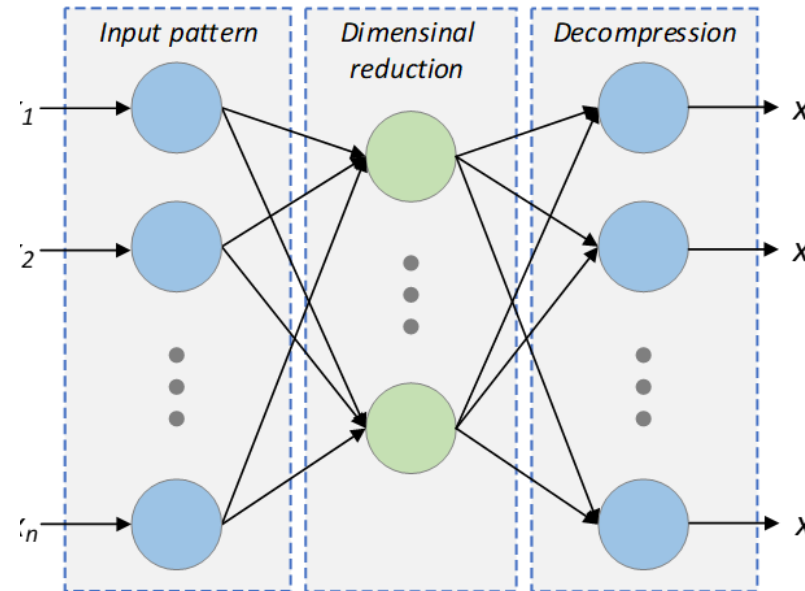
$$v^\lambda : \{\lambda v + (1 - \lambda)c \mid v \in CH(X)\}$$

# Based on One-class techniques

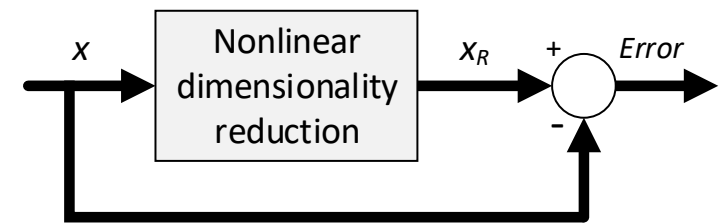
Anomaly detection based on One-class techniques

## Implementation

- One-class techniques.
  - ACH.
  - Autoencoder.



$$v = f_1(W_1x + b_1)$$
$$x_r = f_2(W_2v + b_2)$$

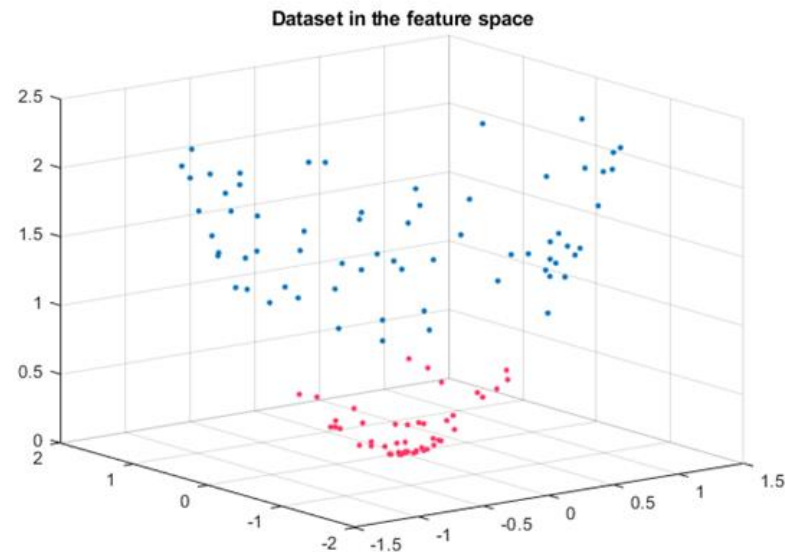


# Based on One-class techniques

Anomaly detection based on One-class techniques

## Implementation

- One-class techniques.
  - ACH.
  - Autoencoder.
  - SVM.



$$\min \left( 0.5 \|w\|^2 + \frac{1}{\nu l} \sum_{i=1}^l \xi_i - b \right)$$

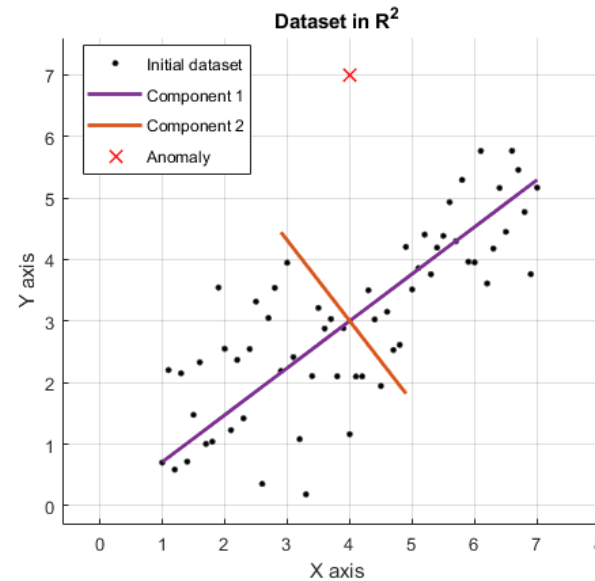
$$(w \cdot \delta(x_i)) \geq b - \xi_i, \xi_i \geq 0$$

# Based on One-class techniques

Anomaly detection based on One-class techniques

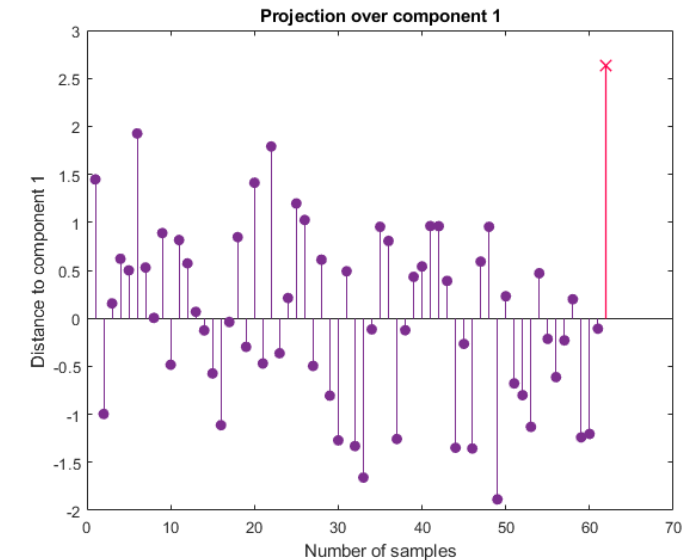
## Implementation

- One-class techniques.
  - ACH.
  - Autoencoder.
  - SVM.
  - PCA.



$$\min \left( 0.5 \|w\|^2 + \frac{1}{\nu l} \sum_{i=1}^l \xi_i - b \right)$$

$$(w \cdot \delta(x_i)) \geq b - \xi_i, \xi_i \geq 0$$



$$e(x) = \|x - x_{pr}\|$$

# Based on One-class techniques

Anomaly detection based on One-class techniques

## Implementation

- One-class techniques.
  - ACH.
  - Autoencoder.
  - SVM.
  - PCA.
- **Validation**

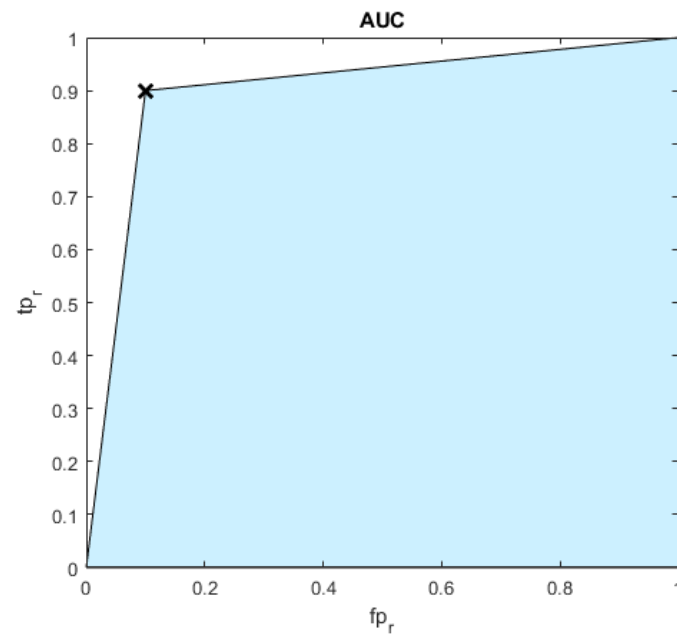
		Predicted class		
		Positive	Negative	
Real class	Positive	True Positives ( <i>TP</i> )	False Negatives ( <i>FN</i> )	$TP+FN=P$
	Negative	False Positives ( <i>FP</i> )	True Negatives ( <i>TN</i> )	$FP+TN=N$

# Based on One-class techniques

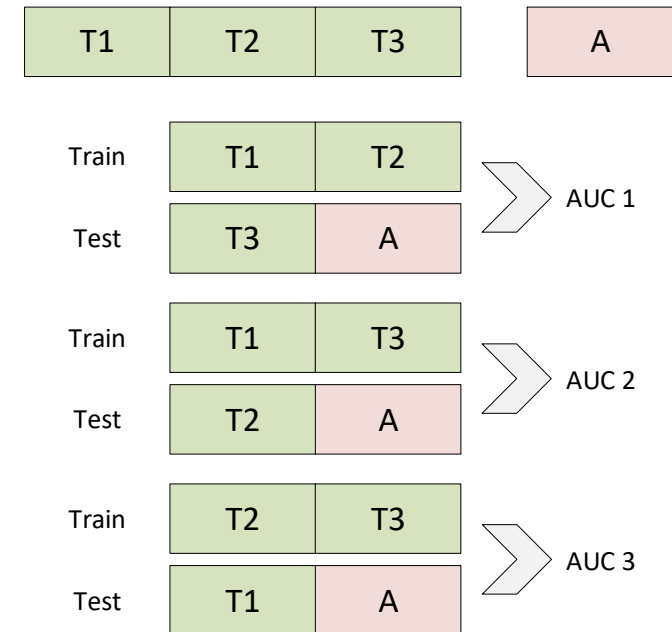
Anomaly detection based on One-class techniques

## Implementation

- One-class techniques.
  - ACH.
  - Autoencoder.
  - SVM.
  - PCA.
- **Validation**



Tpr – True positive rate  
Fpr – False positive rate



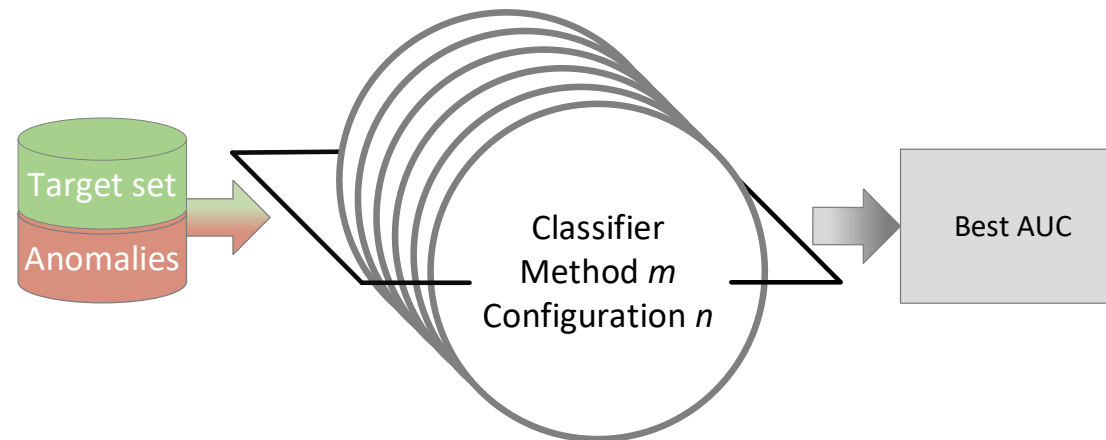


# Based on One-class techniques

Anomaly detection based on One-class techniques

## Implementation

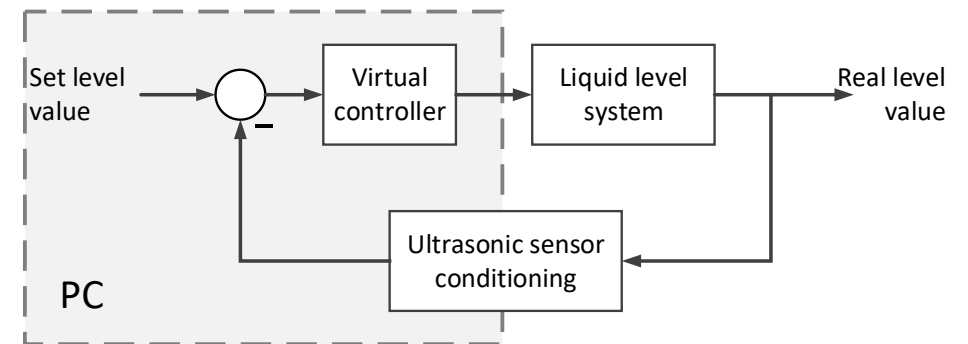
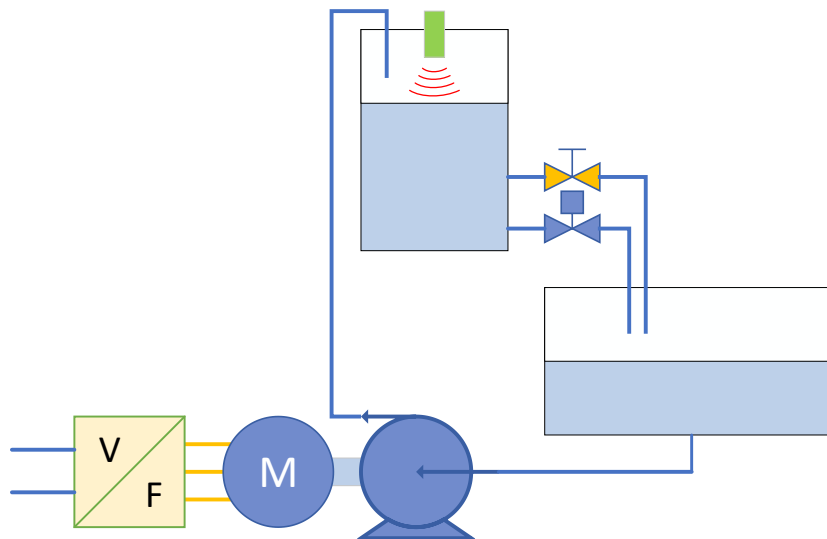
- One-class techniques.
  - ACH.
  - Autoencoder.
  - SVM.
  - PCA.
- Validation
- **Best Configuration**



# Based on One-class techniques

Anomaly detection based on One-class techniques

Anomaly detection based on one-class intelligent techniques over a control level plant → Real case of application



Monitored variables.

- Control signal.
- Error signal.
- Plant coefficients.
- Set point.
- Process value.

# Based on One-class techniques

Anomaly detection based on One-class techniques

## Dataset

- Target set: electric valve closed: 5400 samples.
- Anomalies.
  - Electric valve open 10 %: 5400 samples.
  - Electric valve open 30 %: 5400 samples.
  - Electric valve open 50 %: 5400 samples.
  - Electric valve open 70 %: 5400 samples.
  - Electric valve open 90 %: 5400 samples.

# Based on One-class techniques

## Anomaly detection based on One-class techniques

### Experiments and results.

- Classifier inputs.
  - Control signal.
  - Error.
  - Plant coefficients.
- Data conditioning.
  - 0 to 1.
  - Z-Score.
- ACH.
  - Expansion parameter  $\lambda$ : 0.9, 1, 1.1.
  - Projections: 5, 10, 50, 100, 500, 1000.
- Autoencoder.
  - Neurons in the hidden layer: 1:1:4.
- SVM.
  - Outlier percentage: 0:1:10.
  - Kernel function: Gaussian.
- Tested anomalies. Valve open (%):
  - 10:20:90.

# Based on One-class techniques

Anomaly detection based on One-class techniques

## Experiments and results.

Projections	$\lambda$	AUC	Training time (min)
1000	1,1	99,78	13,25

Hidden layer neurons	Conditioning	AUC	Training time (min)
4	Z-Score	99,49	8,83

Outlier percentage	Conditioning	AUC	Training time (min)
5	0-1	99,35	1,04

# Conclusions and future work

## Conclusions and future works

- Anomaly and fault detection are very important in general terms
- Explain the anomaly or fault could be complex, but very useful
- Fault-Tolerant Systems are a challenge
- These techniques could have application in some different fields (i.e., traceability, quality assurance, operational control, ...)
- Future works:
  - The real time implementation of systems that have a very high computational cost, like vision-based ones.
  - To apply these techniques over day a day common people problems, like water management



# Thank you



# Intelligent systems for anomaly detection of real cases for production optimizing

José Luis Calvo Rolle



Grupo de Investigación  
Ciencia y Técnica Cibernética



UNIVERSIDADE DA CORUÑA

UNED 2025 - Madrid